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# An EPTAS for scheduling jobs on uniform processors: using an MILP relaxation with a constant number of integral variables * 

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#### Abstract

We present an efficient polynomial time approximation scheme (EPTAS) for scheduling on uniform processors, i.e. finding a minimum length schedule for a set of $n$ independent jobs on $m$ processors with different speeds (a fundamental NP-hard scheduling problem). The previous best polynomial time approximation scheme (PTAS) by Hochbaum and Shmoys has a running time of $(n / \epsilon)^{O\left(1 / \epsilon^{2}\right)}$. Our algorithm, based on a new mixed integer linear programming (MILP) formulation with a constant number of integral variables and an interesting rounding method, finds a schedule whose length is within a relative error $\epsilon$ of the optimum, and has running time $2^{O\left(1 / \epsilon^{2} \log (1 / \epsilon)^{3}\right)}+\operatorname{poly}(n)$.


## 1 Introduction

We consider the following fundamental problem in scheduling theory. Suppose that we are given a set $\mathcal{J}$ of $n$ independent jobs $J_{j}$ with processing time $p_{j}$ and a set $\mathcal{P}$ of $m$ non-identical processors $P_{i}$ that run at different speeds $s_{i}$. If job $J_{j}$ is executed on processor $P_{i}$, the machine needs $p_{j} / s_{i}$ time units to complete the job. The problem is to find an assignment $a: \mathcal{J} \rightarrow \mathcal{P}$ for the jobs to the processors that minimizes the total execution time, $\max _{i=1, \ldots, m} \sum_{J_{j}: a\left(J_{j}\right)=P_{i}} p_{j} / s_{i}$. This is the minimum time needed to complete the execution of all jobs on the processors. The problem is denoted $Q \| C_{\max }$ and it is also called the minimum makespan problem on uniform parallel processors. We may assume that the number $m$ of processors is bounded by the number of jobs (otherwise select only the fastest $n$ machines in $O(m)$ time). Furthermore, for simplicity we suppose that $s_{1} \geq s_{2} \geq \ldots \geq s_{m}$ (otherwise we have to sort the speed values).

Results. The problem for uniform (and also identical) processors has been demonstrated to be NP-hard [17, 20] and the existence of a polynomial time algorithm for it would imply $P=N P$. Hochbaum and Shmoys [23, 24] presented a family of polynomial time approximation algorithms $\left\{A_{\epsilon} \mid \epsilon>0\right\}$ for scheduling on identical and uniform processors, where each algorithm $A_{\epsilon}$ generates a

[^0]schedule of length $(1+\epsilon) O P T(I)$ for each instance $I$ and has running time polynomial in the input size $|I|$. Such a family of algorithms is called a polynomial time approximation scheme (PTAS). It is allowed that the running time of each algorithm $A_{\epsilon}$ is exponential in $1 / \epsilon$. In fact, the running time of the PTAS for uniform processors by Hochbaum and Shmoys [24] is $(n / \epsilon)^{O\left(1 / \epsilon^{2}\right)}$. If $\epsilon$ is small, then the running time of the algorithm can be very large.

Two restricted classes of approximation schemes were defined that avoid this problem. An efficient polynomial time approximation scheme (EPTAS) is a PTAS with running time $f(1 / \epsilon)$ poly $(|I|)$ (for some function $f$ ), while a fully polynomial time approximation scheme (FPTAS) runs in time $\operatorname{poly}(1 / \epsilon,|I|)$ (polynomial in $1 / \epsilon$ and the size $|I|$ of the instance). Since the scheduling problem on uniform (and also identical) processors is NP-hard in the strong sense (as it contains bin packing and 3-partition as special cases) [17], we cannot hope for an FPTAS. For identical processors, Hochbaum and Shmoys (see [22]) and Alon at el. [1] gave an EPTAS with running time $f(1 / \epsilon)+O(n)$, where $f$ is doubly exponential in $1 / \epsilon$. The existence of an EPTAS for uniform processors is mentioned as an open problem by Epstein and Sgall [10]. Our main result is the following:

Theorem 1.1 There is an EPTAS (a family of algorithms $\left\{A_{\epsilon} \mid \epsilon>0\right\}$ ) which, given an instance $I$ of $Q \| C_{\text {max }}$ with $n$ jobs and $m$ processors with different speeds and a positive number $\epsilon>0$, produces a schedule for the jobs of length $A_{\epsilon}(I) \leq(1+\epsilon) O P T(I)$. The running time of $A_{\epsilon}$ is

$$
2^{O\left(1 / \epsilon^{2} \log (1 / \epsilon)^{3}\right)}+\operatorname{poly}(n)
$$

Interestingly, the running time of the EPTAS is only single exponential in $1 / \epsilon$. For an introduction to the efficiency of polynomial time approximation schemes we refer to Cesati and Trevisan [2], for an overview of parameterized complexity to Downey and Fellows [7] and Flum and Grohe [13], and for a recent survey of parameterized complexity and approximation algorithms see Marx [31]. For a survey about complexity, algorithms and approximability of machine scheduling problems we refer to a review by Chen, Potts and Woeginger [4].

Most of the work on this fundamental scheduling problem has been done already more than 20 years ago. Horowitz and Sahni [25] proposed an approximation scheme for scheduling on a fixed number $m$ of uniform processors (with running time $(n / \epsilon)^{O(m)}$ ). Gonzales, Ibara, and Sahni [18] in 1977 analyzed LPT (largest processing time) list schedules on uniform processors and proved that LPT produces a schedule of length between 1.5 and 2 times the optimum. Friesen and Langston [15] analyzed a variation of the MULTIFIT algorithm derived from bin packing and proved that its worst-case performance bound is within 1.4 of the optimum. This has been later improved to 1.38 by Chen [3].

Hochbaum and Shmoys [23] introduced the dual approximation approach for identical and uniform processors and used the relationship between these scheduling problems and the bin packing problem. This relationship between scheduling on identical processors and bin packing problem had been exploited already by Coffman, Garey and Johnson [6]. For other work on scheduling on identical processors we refer to $[14,16,19]$. Using the dual approximation approach, Hochbaum and Shmoys [23] proposed a PTAS for scheduling on identical processors with running time $(n / \epsilon)^{O\left(1 / \epsilon^{2}\right)}$. The main idea in their approach is to guess the length of the schedule by using binary search and to consider the corresponding bin packing instance (with scaled identical bin size equal to 1 ). Then they distinguish between large items with size $>\epsilon$ and small items with size $\leq \epsilon$. For the large items they use a dynamic programming approach to calculate the minimum number of bins needed to pack them all. Afterwards, they pack the remaining small items in a greedy way in enlarged bins of size $1+\epsilon$ (i.e. they pack into any bin that currently contains items of total size at most 1 ; and if no such bin exists, then they open a new bin).

The time complexity has been improved to $(n / \epsilon)^{O(1 / \epsilon \log (1 / \epsilon))}$ by Leung [30]. Hochbaum and Shmoys (see [22]) and Alon at al. [1] achieved an improvement to linear time by using an integer linear program for the cutting stock formulation of bin packing for the large items and a result on integer linear programming with a fixed number of variables by Lenstra [28]. This gives an EPTAS for identical processors with running time $f(1 / \epsilon)+O(n)$ where $f$ is doubly exponential in $1 / \epsilon$.

For uniform processors, the decision problem for the scheduling problem with makespan at most $T$ can be viewed as a bin packing problem with different bin sizes. Using an $\epsilon$-relaxed version of this bin packing problem, Hochbaum and Shmoys [24] were also able to obtain a PTAS for scheduling on uniform processors with running time $(n / \epsilon)^{O\left(1 / \epsilon^{2}\right)}$. The main underlying idea in their algorithm is a nice rounding technique and a non-trivial dynamic programming approach over the different bins ordered by their sizes.

Methods. We use the dual approximation method by Hochbaum and Shmoys [24] to transform the scheduling problem into a bin packing problem with different bin sizes. Next, we structure the input by rounding bin sizes and processing times to values of the form $(1+\delta)^{i}$ and $\delta(1+\delta)^{i}$ with $i \in \mathbb{Z}$, respectively. After sorting the bins according to their sizes, $c_{1} \geq \ldots \geq c_{m}$, we build three groups of bins: $\mathcal{B}_{1}$ with the largest $K$ bins (where $K$ is constant). Let $G$ be the smallest index such that capacity $c_{K+G+1} \leq \gamma c_{K}$ where $\gamma<1$ depends on $\epsilon$ (such an index $G$ exists for $c_{m} \leq \gamma c_{K}$ ). In this case $\mathcal{B}_{2}$ is with the set of the next $G$ largest bins (where the maximum size $c_{\max }\left(\mathcal{B}_{2}\right)=c_{K+1}$ divided by the minimum size $c_{\text {min }}\left(\mathcal{B}_{2}\right)=c_{K+G}$ is bounded by a constant $1 / \gamma$ and $\mathcal{B}_{3}$ is the set with the remaining smaller bins (of size smaller than $\gamma c_{K}$ ). This generates a gap of constant size between the capacities of bins in $\mathcal{B}_{1}$ and $\mathcal{B}_{3}$. If the rate $c_{m} / c_{K}$ (where $c_{m}$ is the smallest bin size) is larger the constant $\gamma$, then we obtain a simpler instance with only two groups $\mathcal{B}_{1}$ and $\mathcal{B}_{2}$ of bins.

For $\mathcal{B}_{1}$ we compute all packings for the very large items (those which only fit there). If there is a feasible packing, then we set up a mixed integer linear program (MILP), or an integer linear program (ILP) in the simpler case, to place the other items into the bins. The placement of a large item into the second group $\mathcal{B}_{2}$ is done via integral configuration variables (similar to the ILP formulation for bin packing by Fernandez de la Vega and Lueker [11]). We use fractional configuration variables for the placement of large items into $\mathcal{B}_{3}$. Furthermore, we use additional fractional variables to place small items into $\mathcal{B}_{1}, \mathcal{B}_{2}$, and $\mathcal{B}_{3}$. The MILP (and the ILP in the simpler case) has only a constant number of integral variables and, therefore, can be solved via the algorithm by Lenstra or Kannan [28, 27].

In order to avoid that the running time is doubly exponential in $1 / \epsilon$, we use a recent result by Eisenbrand and Shmonin [9] about integer cones. To apply their result we consider a system of equalities for the integral configuration variables and round the corresponding coefficients. Then each feasible solution of the modified MILP and ILP contains at most $O\left(1 / \delta \log (1 / \delta)^{2}\right)$ integral variables with values larger than zero. By choosing the strictly positive integral variables in the MILP and ILP, we are able to reduce the number of integral configuration variables from $2^{O(1 / \delta \log (1 / \delta))}$ to $O\left(1 / \delta \log (1 / \delta)^{2}\right)$. The number of choices is bounded by $2^{O\left(1 / \delta^{2} \log (1 / \delta)^{3}\right)}$. Next, we consider a rounded version of the modified smaller MILP and ILP formulations in order to solve the corresponding LP feasibility problem more efficiently. Although we still have a huge number of variables, one can solve the LP feasibility problem for the MILP via the separation problem of the dual linear program and then using techniques from Grötschel, Lovasz and Schrijver [21].

Afterwards, we round the fractional variables in the MILP solution to integral values. In the first phase of the rounding we reduce the number of strictly positive fractional configuration variables for each block $B_{\ell}$ (that contains bins with similar capacities) from $2^{O(1 / \delta \log (1 / \delta))}$ to $O(1 / \delta \log (1 / \delta))$ using ideas from [26]. Afterwards we round down each such fractional variable to the next smaller integral value. In the second phase we transform a system of (in-)equalities for the other variables corresponding to the packing of the small items into a scheduling problem on unrelated machines.

The fractional solution of the scheduling problem can be rounded into another solution with only few fractional values using ideas from [32]. The corresponding remaining fractional variables in the system of (in-)equalities are rounded down again to the next integral values. The effect of the rounding is that most of the items can be placed directly into the bins. Only a few of them cannot be placed this way, and here is where the $K$ largest bins and the gap between $\mathcal{B}_{1}$ and $\mathcal{B}_{3}$ come into play. We prove that these items can be moved to the $K$ largest bins by increasing their size only slightly.

Organization of the paper. In Section 2 we give definitions, notations and show how to structure the input and how to define the three bin groups. In Section 3, we consider the simpler case with only two bin groups and the property that the bins in the second group have a constant number of different capacities. In this simpler case we describe an ILP formulation (see Section 3.1); we show how to solve this ILP and give the first ideas to place items into the bins (see Section 3.2). In Section 4 we consider the more general case with three groups of bins. In Section 4.1 we set up our MILP relaxation and in Section 4.2 we show how to solve it. Then in Section 4.3 we describe the rounding technique and in Section 4.4 we show how to pack the jobs via the rounded MILP solution. Here we bound also the total size of items that cannot be placed directly into bins.

## 2 Modifying the input

First, we compute a 2 -approximate solution using the algorithm by Gonzales et al. [18]. It generates a schedule of length $B(I) \leq 2 O P T(I)$. Then take the interval $[B(I) / 2, B(I)]$ and use binary search to test values for the optimum or approximate schedule. In the following we choose a value $\delta<\epsilon$ such that $1 / \delta$ is integral (we specify the value later). Notice that $O P T(I) \in[B(I) / 2, B(I)]$ and that the length $(\delta / 2) B(I) \leq \delta O P T(I)$. That implies that the interval $[B(I) / 2, B(I)]$ can be divided into $1 / \delta$ subintervals of length $\delta B(I) / 2$ and that there is at least one subinterval $[B(I) / 2+$ $i(\delta / 2) B(I), B(I) / 2+(i+1)(\delta / 2) B(I)]$ with $i \in\{0, \ldots, 1 / \delta-1\}$ that contains the optimum length $O P T(I)$. To find one of these intervals, we use a standard dual approximation method that for each value $T$ either computes an approximate schedule of length $T(1+\alpha \delta)$ (where $\alpha$ is a constant) or shows that there is no schedule of length $T$.

The scheduling problem can be transformed into a bin packing problem with variable bin sizes as described by Hochbaum and Shmoys [24]. For a given value $T$ for the makespan we can generate $m$ bins with capacities $c_{i}=T \cdot s_{i}$. Using the ordering of the speed values we have $c_{1} \geq c_{2} \geq \ldots \geq c_{m}$. The goal is now to find a packing for the jobs into these $m$ bins. Let us round the processing time $p_{j}$ of each job to the next pale $\bar{p}_{j}$ of the form $\delta(1+\delta)^{k_{j}}$ with $k_{j} \in \mathbb{Z}$, so $p_{j} \leq \bar{p}_{j}=\delta(1+\delta)^{k_{j}} \leq(1+\delta) p_{j}$. If we have a subset $A$ of jobs with $\sum_{j \in A} p_{j} \leq c_{i}$, then the total increased processing time $\sum_{j \in A} \bar{p}_{j}$ is bounded by $c_{i}(1+\delta)$. Furthermore, we can round the enlarged capacities $c_{i}(1+\delta)$ to the next power $c_{i}^{\prime}$ of $(1+\delta)$. That implies $c_{i}(1+\delta) \leq c_{i}^{\prime}=(1+\delta)^{\ell_{i}} \leq c_{i}(1+\delta)^{2}$ with $\ell_{i} \in \mathbb{Z}$. By normalization we may suppose that the minimum capacity $c_{\text {min }}^{\prime}=\min _{i=1, \ldots, m} c_{i}^{\prime}=1$.

Lemma 2.1 If there is a feasible packing of $n$ jobs with processing times $p_{j}$ into $m$ bins with capacities $c_{1} \geq \ldots \geq c_{m}$, then there is also a packing of $n$ jobs with rounded processing times $\bar{p}_{j}=\delta(1+\delta)^{k_{j}} \leq(1+\delta) p_{j}$ into $m$ bins with rounded bin capacities $c_{i}^{\prime}=(1+\delta)^{\ell_{i}} \leq c_{i}(1+\delta)^{2}$.

Notice that the exponent $k_{j}$ in $\bar{p}_{j}=\delta(1+\delta)^{k_{j}}$ can be negative. For $k_{j}<0$ the processing time of a job is smaller than $\delta$ and small compared to the capacities of all bins. These jobs will be handled as tiny jobs in a special way (see end of this Section). In the next step we divide the bins into different bin groups. The first bin group $\mathcal{B}_{1}$ consists of the $K$ largest bins, where $K=O(1 / \delta \log (1 / \delta))$. If
$c_{\max }(\mathcal{B}) / c_{\min }(\mathcal{B})$ is bounded by a constant $C$, then by using the following Lemma there is only a constant number $O(\log C / \delta)$ of different capacities in bin group $\mathcal{B}$.

Lemma 2.2 If $c_{\max }(\mathcal{B}) / c_{\min }(\mathcal{B}) \leq C$ for some constant $C$ and the set of capacities in $\mathcal{B}$ is $c(\mathcal{B})=$ $\left\{(1+\delta)^{x},(1+\delta)^{x+1}, \ldots,(1+\delta)^{y}\right\}$ with $x, y \in \mathbb{Z}^{+}$and $x<y$, then $|c(\mathcal{B})| \leq 2 \log (C) / \delta+1$ for any $\delta \in(0,1 / 2]$.

Proof: Using the assumption on $\mathcal{B}, c_{\max }(\mathcal{B}) / c_{\min }(\mathcal{B})=(1+\delta)^{y-x} \leq C$. Therefore, the number of elements $(1+\delta)^{i}$ in $\mathcal{B}$ is equal to

$$
y-x+1 \leq \log (C) / \log (1+\delta)+1 \leq 2 \log (C) / \delta+1 ;
$$

for the second inequality we use $\log (1+\delta) \geq \delta-\delta^{2} \geq \delta / 2$ for $\delta \in(0,1 / 2]$.
If $c_{\min }(\mathcal{B}) / c_{\max }\left(\mathcal{B}^{\prime}\right) \geq C$ for two bin groups $\mathcal{B}$ and $\mathcal{B}^{\prime}$ with $C>1$, then there is a gap of size $C$ between the capacities of the bins in the two groups. Depending on another constant $\gamma$ (where $\left.\gamma=\Theta\left(\delta^{2}\right)\right)$ we obtain either two or three bin groups:

Case 1: There is at least one bin with capacity at most $\gamma c_{K}^{\prime}$. Let $G$ be the smallest index such that $c_{K+G+1}^{\prime} \leq \gamma c_{K}^{\prime}$. This implies that $c_{K+G}^{\prime}>\gamma c_{K}^{\prime}$. In this case we have three groups of bins: $\mathcal{B}_{1}=\left\{b_{1}, \ldots, b_{K}\right\}, \mathcal{B}_{2}=\left\{b_{K+1}, \ldots, b_{K+G}\right\}$, and $\mathcal{B}_{3}=\left\{b_{K+G+1}, \ldots, b_{m}\right\}$. Notice that $\mathcal{B}_{2}$ has a constant number of different capacities (using $c_{K+1}^{\prime} / c_{K+G}^{\prime} \leq c_{K+1}^{\prime} / \gamma c_{K}^{\prime} \leq 1 / \gamma$ ). In addition we obtain a gap of at least $1 / \gamma$ between the capacities in $\mathcal{B}_{1}$ and $\mathcal{B}_{3}$.

Case 2: All bins have capacity larger than $\gamma c_{K}^{\prime}$. This implies that $c_{m}^{\prime}>\gamma c_{K}^{\prime}$. In this case we have only two groups of bins $\mathcal{B}_{1}=\left\{b_{1}, \ldots, b_{K}\right\}$ and $\mathcal{B}_{2}=\left\{b_{K+1}, \ldots, b_{m}\right\}$. In this case $\mathcal{B}_{2}$ has a constant number of different capacities (using $c_{K+1}^{\prime} / c_{m}^{\prime} \leq c_{K+1}^{\prime} / \gamma c_{K}^{\prime} \leq 1 / \gamma$ ).

Let $\mathcal{B}_{1}^{\prime}=\left\{b_{1}, \ldots, b_{K^{\prime}}\right\}$ be the subset of $\mathcal{B}_{1}$ with the bins that have capacity larger than $\delta /(K-$ 1) $c_{\max }\left(\mathcal{B}_{1}\right)$. By a further modification of the bin packing instances we obtain the following result.

Lemma 2.3 If there a solution for the original instance $(\mathcal{J}, \mathcal{M})$ of our scheduling problem with makespan $T$ and corresponding bin sizes $c_{1} \geq \ldots \geq c_{m}$, then there is a feasible packing for instance $\left(\mathcal{J}, \mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2} \cup \mathcal{B}_{3}\right)$ or instance $\left(\mathcal{J}, \mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right)$ with rounded bin capacities $\bar{c}_{i}=(1+\delta)^{\bar{q}_{i}} \leq c_{i}(1+\delta)^{3}$ and rounded processing times $\bar{p}_{j}=\delta(1+\delta)^{k_{j}} \leq(1+\delta) p_{j}$. In addition we have one of the following four scenarios:

1. two bin groups $\mathcal{B}_{1}^{\prime}$ and $\mathcal{B}_{2}$ with gap of $1 / \delta$ between $c_{\min }\left(\mathcal{B}_{1}^{\prime}\right)$ and $c_{\max }\left(\mathcal{B}_{2}\right)$ and constant number of different capacities in $\mathcal{B}_{2}$.
2. two bin groups $\mathcal{B}_{1}^{\prime}$ and $\mathcal{B}_{2}$ with a constant number of different capacities in $\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}$.
3. three bin groups $\mathcal{B}_{1}^{\prime}, \mathcal{B}_{2}, \mathcal{B}_{3}$ with gap of $1 / \delta$ between $c_{\min }\left(\mathcal{B}_{1}^{\prime}\right)$ and $c_{\max }\left(\mathcal{B}_{2}\right)$ and gap of $1 / \gamma$ between $c_{\text {min }}\left(\mathcal{B}_{1}\right)$ and $c_{\max }\left(\mathcal{B}_{3}\right)$. Furthermore $\mathcal{B}_{2}$ has a constant number of different capacities.
4. three bin groups $\mathcal{B}_{1}^{\prime}, \mathcal{B}_{2}$ and $\mathcal{B}_{3}$ with gap of $1 / \gamma$ between $c_{\text {min }}\left(\mathcal{B}_{1}\right)$ and $c_{\text {max }}\left(\mathcal{B}_{3}\right)$ and constant number of different capacities in $\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}$.

Proof: Depending on the constant $\gamma$ we have obtained either an instance with three or two bin groups. Let us consider now the largest $K$ bins more carefully. The maximum capacity $c_{\max }\left(\mathcal{B}_{1}\right)$ is equal to $c_{1}^{\prime}$. If there are bins in $\mathcal{B}_{1}$ with capacity $<(\delta /(K-1)) c_{\max }\left(\mathcal{B}_{1}\right)$, then we may take all jobs placed into these bins and put them on top of $b_{1}$. The total load of these jobs is at most $((K-1) \delta /(K-1)) c_{1}^{\prime}=\delta c_{1}^{\prime}$. In order to store these jobs we enlarge the capacity of the first bin $b_{1}$ to $\bar{c}_{1}=(1+\delta) c_{1}^{\prime}$. All other capacities remain the same, i.e. $\bar{c}_{i}=c_{i}^{\prime}$ for $i>1$. Using Lemma 2.2
we obtain a feasible packing of all $n$ jobs into the bins with enlarged and rounded capacities. Next we analyze the structure of the instances with two or three bin groups in more detail. We have two interesting cases corresponding to $c_{\max }\left(\mathcal{B}_{1}^{\prime}\right)=(1+\delta) c_{1}^{\prime}$ and $c_{K+1}^{\prime}$ :

Case A: $c_{K+1}^{\prime}<\left(\delta^{2} /((K-1)(\delta+1))\right) c_{\max }\left(\mathcal{B}_{1}^{\prime}\right)$. In this case all remaining bins in $\mathcal{B}_{1}^{\prime}$ have capacity larger than $c_{\min }\left(\mathcal{B}_{1}^{\prime}\right) \geq(\delta /((K-1)(\delta+1))) c_{\max }\left(\mathcal{B}_{1}^{\prime}\right)$ and all bins in $\mathcal{B}_{2}$ have capacity $\leq c_{K+1}^{\prime}<\delta c_{\min }\left(\mathcal{B}_{1}^{\prime}\right)$. This implies that we have now a gap of $1 / \delta$ between the capacities of the bins in $\mathcal{B}_{1}^{\prime}$ and $\mathcal{B}_{2}$.

Case B: $c_{K+1}^{\prime}>\left(\delta^{2} /((K-1)(\delta+1))\right) c_{\max }\left(\mathcal{B}_{1}^{\prime}\right)$. In addition we know that $c_{K+G}^{\prime} / c_{K+1}^{\prime} \geq \gamma$ in case 1 and $c_{m}^{\prime} / c_{K+1} \geq \gamma$ in case 2. This implies that $c_{\max }\left(\mathcal{B}_{1}^{\prime}\right) / c_{\min }\left(\mathcal{B}_{2}\right) \leq(K-1)(\delta+1) /\left(\gamma \delta^{2}\right)$ in both cases. This implies that we have only a constant number of different capacities in $\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}$.

In scenario 2 and $4, c_{\max }\left(\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right) / c_{\text {min }}\left(\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right)$ is bounded by $(K-1)(\delta+1) /\left(\gamma \delta^{2}\right)=O\left(K /\left(\gamma \delta^{2}\right)\right)$. On the other hand, in scenario 1 and 3 we have $c_{\max }\left(\mathcal{B}_{2}\right) / c_{\min }\left(\mathcal{B}_{2}\right) \leq 1 / \gamma$. If there are less than $K=O(1 / \delta \log (1 / \delta))$ bins in the instance, then we can apply the algorithm for scenario 1 where $\mathcal{B}_{1}^{\prime}$ contains $K^{\prime} \leq K$ bins and $\mathcal{B}_{2}=\emptyset$.

In the LP relaxation later we use only the larger bins in $\mathcal{B}_{1}^{\prime}$, but in the final rounding step we may also use the smaller bins in $\mathcal{B}_{1}$. A packing of jobs into bin $b_{i}$ with capacity $\bar{c}_{i} \leq c_{i}(1+\delta)^{3}$ corresponds to a schedule for the jobs on processor $P_{i}$ with load at most $\bar{c}_{i} / s_{i} \leq c_{i}(1+\delta)^{3} / s_{i}=T(1+\delta)^{3}$. In other words, a packing into bins with enlarged capacities for $T \leq(1+\delta) O P T(I)$ gives us a schedule of length $\leq T(1+\delta)^{3} \leq O P T(1+\delta)^{4}$. For $T \leq O P T(1+\delta)$, our algorithm (as described in Section 3 and 4) generates a schedule of length at most $T(1+\alpha \delta)$, where $\alpha$ is a constant, or asserts that there is no schedule of length $T$. For $\delta \leq \min (\epsilon /(\alpha+2), 1)$, this implies in the first case a schedule of length at most $\leq T(1+\alpha \delta) \leq O P T(1+\alpha \delta)(1+\delta) \leq O P T(1+(\alpha+2) \delta) \leq O P T(1+\epsilon)$.

Notice that we have a set $\mathcal{J}_{\text {tiny }}$ of jobs with tiny processing time $\leq \delta \bar{c}_{m}$. Let $S_{\text {tiny }}$ be the total size of tiny jobs, i.e. $S_{\text {tiny }}=\sum_{J_{j} \in \mathcal{J}_{\text {tiny }}} \bar{p}_{j}$. If there is a feasible schedule with makespan $T$, then the total processing time $\sum_{j \in \mathcal{J}} \bar{p}_{j}$ is smaller or equal to the total area of the corresponding bins $\sum_{i=1}^{m} \bar{c}_{i}$. If this inequality does not hold, then we can discard the choice with makespan $T$ (in fact we have to increase the makespan in this case). Therefore, we can eliminate in a first step all tiny jobs. If there exists a packing for the other jobs into bins of size $\bar{c}_{i}$, then we can generate a feasible packing for all jobs into enlarged bins of size $\bar{c}_{i}(1+\delta)$. This can be done by a greedy algorithm that packs the tiny jobs into the free space left (by allowing to use an additional $\delta$-fraction of the capacities). This works, since the processing time of each tiny job is at most $\delta \bar{c}_{m} \leq \delta \bar{c}_{i}$ for $i=1, \ldots, m$ and the inequality above holds.

## 3 Solution for simpler instance $\left(\mathcal{J}^{\prime}, \mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right)$

In this section we mainly study scenario 1 (for an illustration see also Figure 1). Note that scenario 2 can be seen as a special case of scenario 1 where $\mathcal{B}_{1}=\emptyset$ (see also the discussion at the end of the section). Let us suppose that $\mathcal{B}_{1}^{\prime}$ contains $K^{\prime} \leq K$ bins with capacities $\bar{c}_{1} \geq \bar{c}_{2} \geq \ldots \geq \bar{c}_{K^{\prime}}$ where $\bar{c}_{K^{\prime}} \geq \delta /((K-1)(\delta+1)) \bar{c}_{1}$ and that $\mathcal{B}_{2}$ contains further bins $\bar{c}_{K+1} \geq \cdots \geq \bar{c}_{m}$ with $\bar{c}_{K+1} \leq \delta \bar{c}_{K^{\prime}}$ (the other bins in $\mathcal{B}_{1}$ with smaller size can be neglected). This means that we have a gap between $\mathcal{B}_{1}^{\prime}$ and $\mathcal{B}_{2}$ (see also Figure 1). In the first part of our algorithm we pre-assign the huge jobs with processing time larger than $\delta \bar{c}_{K^{\prime}}$ to the first $K^{\prime} \leq K$ machines. Using the properties above, there are at most $K^{\prime} \bar{c}_{1} /\left(\delta \bar{c}_{K^{\prime}}\right) \leq K(K-1)(1+\delta) / \delta^{2}$ many such jobs. If there are more jobs, then there is no feasible solution with makespan $T$ and we are done. Here we use also the fact that $\bar{c}_{K+1} \leq \delta \bar{c}_{K^{\prime}}$ and that, therefore, the huge jobs fit only on the first $K^{\prime}$ machines.

Now we have to assign the huge jobs to the first $K^{\prime}$ machines. Since the number of machines $K^{\prime} \leq K=O(1 / \delta \log (1 / \delta))$ and the number of jobs $H \leq K(K-1)(1+\delta) / \delta^{2} \leq O\left(1 / \delta^{4} \log (1 / \delta)^{2}\right)$


Figure 1: Scenario 1.
are both constant (where the values depend on $1 / \epsilon$ ), this can be done in constant time $f(1 / \epsilon)$. A feasible packing of huge jobs is indicated in Figure 2. In fact the number of possible assignments can be bounded by $(1 / \delta \log (1 / \delta))^{O\left(1 / \delta^{4} \log (1 / \delta)^{2}\right)} \leq 2^{O\left(1 / \delta^{4} \log (1 / \delta)^{3}\right)}$. Again, if there is no feasible assignment, then there is no corresponding schedule with makespan $T$. As an alternative we compute an approximate solution with accuracy $\rho$ for the huge jobs. For this step we either could use the PTAS for scheduling on uniform machines [24] or an FPTAS for scheduling on unrelated machines [12]. The running time of the PTAS for uniform machines with a constant number of jobs (as above calculated) is $\left(1 / \delta^{4} \log (1 / \delta)^{2}\right)^{O\left(1 / \rho^{2}\right)} \leq 2^{O\left(1 / \rho^{2} \log (1 / \delta)\right)}=2^{O\left(1 / \delta^{2} \log (1 / \delta)\right)}$ (using $\rho=\delta$ ). On the other hand, this increases the first $K^{\prime}$ bin capacities from $\bar{c}_{i}$ to $\bar{c}_{i}(1+\delta)$ for $i=1, \ldots, K^{\prime}$ and the makespan from $T(1+\delta)^{3}$ to $T(1+\delta)^{4}$.

### 3.1 The ILP formulation

After the assignment for the huge jobs $J_{1}, \ldots, J_{H}$ we have a free area of $S_{0}=\sum_{i=1}^{K^{\prime}} \bar{c}_{i}(1+\delta)-\sum_{j=1}^{H} \bar{p}_{j}$ in $\mathcal{B}_{1}^{\prime}$ for the remaining jobs with processing time $\bar{p}_{j} \leq \delta \bar{c}_{K^{\prime}}$. A subset of these remaining jobs will be placed later in a greedy way on the first $K^{\prime}$ machines. But before, we set up an integer linear program (ILP) for the bins in $\mathcal{B}_{2}$. Suppose that the set of different capacities in $\mathcal{B}_{2}$ is denoted by $\{\bar{c}(1), \ldots, \bar{c}(L)\}=\left\{\bar{c}_{K+1}, \ldots, \bar{c}_{m}\right\}($ where $\bar{c}(1)>\bar{c}(2)>\ldots>\bar{c}(L))$. In this case $\bar{c}(1)=\bar{c}_{K+1}=c_{K+1}^{\prime}$ and $\bar{c}(L)=\bar{c}_{m}=c_{m}^{\prime}$.

Let $m_{1}, \ldots, m_{L}$ be the number of machines (bins) of size $\bar{c}(\ell)=(1+\delta)^{r_{\ell}}$ for $\ell=1, \ldots, L$. The $m_{\ell}$ machines of the same speed form a block $B_{\ell}$ of bins with the same capacity $\bar{c}(\ell)$. Note that we specify in the following the capacity of a bin group by $\bar{c}(\ell)$. In addition we have $n_{1}, \ldots, n_{P}$ of jobs with size $\delta(1+\delta)^{k_{j}}$ for $j=1, \ldots, P$ (all of size $>\delta(1+\delta)^{r_{L}}$ and $\leq \delta \bar{c}_{K^{\prime}}$ ). Notice that jobs with size within $\left((1+\delta)^{r_{1}}, \delta \bar{c}_{K^{\prime}}\right)$ cannot be packed into bins of $\mathcal{B}_{2}$. Suppose that the first $P^{\prime} \leq P$ job sizes are larger than $(1+\delta)^{r_{1}}=\bar{c}_{K+1}$. These (non-huge) jobs will be placed later via the ILP into the first $K^{\prime}$ bins or block $B_{0}$.


Figure 2: Packing huge jobs.
In the ILP below we use $C_{1}^{(\ell)}, \ldots, C_{h_{\ell}}^{(\ell)}$ as configurations or multisets with numbers $\delta(1+\delta)^{j} \in$ $\left[\delta(1+\delta)^{r_{\ell}},(1+\delta)^{r_{\ell}}\right]$ (these are large processing times corresponding to $B_{\ell}$ ) where the total sum is bounded by $\bar{c}(\ell)=(1+\delta)^{r_{\ell}}$ (the capacity of the bins in block $B_{\ell}$ ). Let $a\left(j, C_{i}^{(\ell)}\right)$ be the number of occurrences of number $\delta(1+\delta)^{j}$ in configuration $C_{i}^{(\ell)}$ and let $\operatorname{size}\left(C_{i}^{(\ell)}\right)=\sum_{j} a\left(j, C_{i}^{(\ell)}\right) \delta(1+\delta)^{j} \leq \bar{c}(\ell)$ be the total sum of the numbers in $C_{i}^{(\ell)}$. In the ILP below we use an integral variable $x_{i}^{(\ell)}$ to indicate the length of the configuration $C_{i}^{(\ell)}$.

Furthermore, we have additional variables to place jobs as small ones into other bins. To do this, for $j>P^{\prime}$ let $a_{j} \in\{1, \ldots, L\}$ be the smallest index such that $\delta(1+\delta)^{k_{j}}$ is at least $\delta(1+\delta)^{r_{a_{j}}}$. For each block $B_{\ell}$ with $\ell \geq a_{j}$, the processing time $\delta(1+\delta)^{k_{j}}$ is large corresponding to the block. If there is no such index, then the processing time $\delta(1+\delta)^{k_{j}}<\delta(1+\delta)^{L}=\delta \bar{c}_{m}$ and we have a tiny job. These jobs are removed in the first step of our algorithm and will be added at the end. Note that a job of size within $\left(\delta(1+\delta)^{r_{1}},(1+\delta)^{r_{1}}\right]$ could be placed as a large job in an approximate or optimal solution into a bin of group $\mathcal{B}_{1}$. In our algorithm we implicitly place such a job as a small job into one of the first $K^{\prime}$ bins. We use variables $y_{j, \ell}$ for $\ell=0,1, \ldots, a_{j}-1$ to indicate the number of jobs of size $\delta(1+\delta)^{k_{j}}$ placed as a small one in block $B_{\ell}$. $B_{0}$ represents here for simplicity the block with the first $K^{\prime}$ bins. The first $P^{\prime}$ job sizes do not fit into the bins in group $\mathcal{B}_{2}$. Therefore, we use for these job sizes only one variable $y_{j, 0}=n_{j}$ and set the index $a_{j}=0$. We use the following ILP:

$$
\begin{array}{lll}
\sum_{i} x_{i}^{(\ell)} & \leq m_{\ell} \quad \text { for } \ell=1, \ldots, L \\
\sum_{\ell, i} a\left(k_{j}, C_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{\ell=0}^{a_{j}-1} y_{j, \ell} & =n_{j} & \text { for } j=P^{\prime}+1, \ldots, P \\
\sum_{i} \operatorname{size}\left(C_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{j: \ell<a_{j}} y_{j, \ell} \delta(1+\delta)^{k_{j}} & \leq m_{\ell} \bar{c}(\ell) & \text { for } \ell=1, \ldots, L \\
\sum_{j=1}^{P} y_{j, 0} \delta(1+\delta)^{k_{j}} & \leq S_{0} &
\end{array}
$$

$$
\begin{aligned}
& x_{i}^{(\ell)} \quad \text { integral } \geq 0 \\
& y_{j, 0} \quad=n_{j} \\
& y_{j, \ell} \text { integral } \geq 0
\end{aligned}
$$

for $\ell=1, \ldots, L$ and $i=1, \ldots, h_{\ell}$
for $j=1, \ldots, P^{\prime}$
for $j=P^{\prime}+1, \ldots, P$ and $\ell=0, \ldots, a_{j}-1$

The first $L$ inequalities guarantee that we use only $m_{\ell}$ bins for each group $B_{\ell}$. The next $P-P^{\prime}$ equalities are used to cover the $n_{j}$ jobs with processing times $\delta(1+\delta)^{k_{j}}$. Here a job is either taken as a large one via the $x_{i}^{(\ell)}$ variables or as a small one via the $y_{j, \ell}$ variables. The next $L$ inequalities bound the total size of all jobs assigned to block $B_{\ell}$ by the area of the $m_{\ell}$ bins with capacity $\bar{c}(\ell)$. The last inequality corresponds to the small jobs that are assigned via the $y_{j, 0}$ variables to block $B_{0}$. These small jobs must have a total area bounded by the free space $S_{0}$ in the first $K^{\prime}$ bins. This is described by the last inequality.

Lemma 3.1 Each feasible packing of the items into the bins of size $\bar{c}_{i}$ corresponds to a feasible solution for the ILP. On the other hand, each feasible solution for the ILP can be transformed into a packing where the bin sizes are enlarged to $(1+2 \delta) \bar{c}_{i}$.

Proof: The first direction is quite obvious. Take out first the items that are small corresponding to a bin. Then the other items can be grouped according to the packing and to their sizes together into configurations for each block $B_{\ell}$. Let $\tilde{x}_{i}^{(\ell)}$ be the number of bins in the packing with configuration $C_{i}^{(\ell)}$ in $B_{\ell}$. Then, the first $L$ inequalities are satisfied automatically. Then, let $\tilde{y}_{j, \ell}$ be the number of small items with size $\delta(1+\delta)^{k_{j}}$ packed in block $B_{\ell}$. Since all items are packed into the bins, the next $P-P^{\prime}$ equalities are also satisfied. In addition the total area of all items packed into block $B_{\ell}$ is exactly $\sum_{i} \operatorname{size}\left(C_{i}^{(\ell)}\right) \tilde{x}_{i}^{(\ell)}+\sum_{j: \ell<a_{j}} \tilde{y}_{j, \ell} \delta(1+\delta)^{k_{j}}$ and, therefore, is bounded by the total area $m_{\ell} \bar{c}(\ell)$ of block $B_{\ell}$. Concerning block $B_{0}$, the total area $\sum_{j} \tilde{y}_{j, 0} \delta(1+\delta)^{k_{j}}$ of the small jobs packed into $B_{0}$ must be smaller than the free space $S_{0}$.

On the other hand, suppose that there is a feasible solution $(\bar{x}, \bar{y})$ for the ILP. Then use $\bar{x}_{i}^{(\ell)}$ bins with configuration $C_{i}^{(\ell)}$ for each $\ell$ and $i$. Using this space we can place $n_{j}-\sum_{\ell=0}^{a_{j}-1} \bar{y}_{j, \ell}$ jobs with processing time $\delta(1+\delta)^{k_{j}}$ (for $\left.j=P^{\prime}+1, \ldots, P\right)$. In addition each block $B_{\ell}$ gets $\bar{y}_{j, \ell}$ jobs with size $\delta(1+\delta)^{k_{j}}$ for each $j$ with $\ell<a_{j}$. We can pack these small jobs into the bins of block $B_{\ell}$ one after another as long as a bin capacity is at most $\bar{c}(\ell)(1+\delta)$. Using the area constraints we know that these jobs fit together with the long ones into each block $B_{\ell}$ for $\ell=1, \ldots, L$. In this procedure we enlarge the capacities of the bins from $\bar{c}_{i}$ to $(1+\delta) \bar{c}_{i}$. Finally, the small jobs with area $\sum_{j=1}^{P} y_{j, 0} \delta(1+\delta)^{k_{j}}$ are placed with the same procedure into the $K^{\prime}$ enlarged bins. This is possible, since the total area (via the last inequality of the ILP) is bounded by $S_{0}$. As above the capacities of the first $K^{\prime}$ bins are enlarged from $\bar{c}_{i}(1+\delta)$ to at most $\bar{c}_{i}(1+\delta)+\delta \bar{c}_{K^{\prime}} \leq(1+2 \delta) \bar{c}_{i}$. Notice that we have already increased the first $K^{\prime}$ capacities for the huge jobs.

Note that we could insert the tiny jobs together with the small jobs at the same time without increasing the capacities a second time. The Lemma above implies that if the ILP has a feasible integral solution then we obtain a feasible packing into bins of capacity $\bar{c}_{i}(1+2 \delta) \leq c_{i}(1+2 \delta)(1+$ $\delta)^{3} \leq c_{i}(1+\delta)^{5}$ and a corresponding schedule of length at most $T(1+\delta)^{5}$.

The set $\mathcal{B}_{2}$ has a constant number of different capacities using the property $c_{\max }\left(\mathcal{B}_{2}\right) / c_{\min }\left(\mathcal{B}_{2}\right) \leq$ $1 / \gamma$ (see also Figure 1). This means that $(1+\delta)^{r_{1}} /(1+\delta)^{r_{L}} \leq 1 / \gamma$. Therefore, $r_{1}>\ldots>r_{L} \geq 0$, $r_{1}-r_{L} \leq O(\log (1 / \gamma) / \delta)$, and $L \leq r_{1}-r_{L}+1 \leq O(\log (1 / \gamma) / \delta) \leq O(1 / \delta \log (1 / \delta))$ using $\gamma=\Theta\left(\delta^{2}\right)$. Furthermore, each configuration contains at most $1 / \delta$ numbers or jobs with large processing times. This implies that the number of configurations is also bounded by a constant that depends on $1 / \delta$.

Lemma 3.2 The number of variables in the ILP is at most $2^{O((1 / \delta) \log (1 / \delta))}$ and the number of constraints is $O((1 / \delta) \log (1 / \delta))$ (not counting the non-negativity constraints). In addition, the cardinality of each set $P_{\ell}$ (the number of large job sizes within block $B_{\ell}$ ) is at most $O(1 / \delta \log (1 / \delta))$.

Proof: Let $P_{\ell}=\left\{j \in\left\{P^{\prime}+1, \ldots, P\right\} \mid \delta(1+\delta)^{k_{j}} \in\left(\delta(1+\delta)^{r_{\ell}},(1+\delta)^{r_{\ell}}\right]\right\}$ be the indices of job sizes that are large corresponding to block $B_{\ell}$ for $\ell \geq 1$. For $\delta \leq 1 / 2$ we have $\left|P_{\ell}\right| \leq\lfloor 2 / \delta \log (1 / \delta)\rfloor$. To see this consider all job sizes $\delta(1+\delta)^{i} \in\left(\delta(1+\delta)^{k},(1+\delta)^{k}\right]$. This is exactly the set $\left\{\delta(1+\delta)^{k+1}, \ldots, \delta(1+\right.$ $\left.\delta)^{k+i-1}\right\}$ with $i-1$ elements, where $\delta(1+\delta)^{k+i}>(1+\delta)^{k}$ and $\delta(1+\delta)^{k+i-1} \leq(1+\delta)^{k}$. Now the first condition is equivalent to $(1+\delta)^{i}>1 / \delta$ or $i>\log _{1+\delta}(1 / \delta)=\log _{2}(1 / \delta) / \log _{2}(1+\delta)$. This implies that the number of job sizes is at most $\left\lfloor\log _{2}(1 / \delta) / \log _{2}(1+\delta)\right\rfloor$. Since $\log _{2}(1+\delta) \geq \delta-\delta^{2} \geq \delta / 2$ for all $\delta \geq-1 / 2$ and $\delta \leq 1 / 2$, we get $\log _{2}(1 / \delta) / \log _{2}(1+\delta) \leq \log _{2}(1 / \delta) /(\delta / 2)=2 / \delta \log _{2}(1 / \delta)$.

The number of configurations in one block $B_{\ell}$ is bounded by $2^{O(1 / \delta \log (1 / \delta))}$. In fact we can describe a configuration by an assignment $f:\{1, \ldots, 1 / \delta\} \rightarrow P_{\ell} \cup\{0\}$. Here $f(i) \in P_{\ell}$ indicates the ith size or processing time used for $i=1, \ldots, 1 / \delta$. If a configuration contains less than $1 / \delta$ sizes, then we can indicate this with $f(i)=0$ for some $i$. The total number of such assignments is bounded by $\left(\left|P_{\ell}\right|+1\right)^{1 / \delta}=2^{O(1 / \delta \log (1 / \delta \log (1 / \delta)))}=2^{O(1 / \delta \log (1 / \delta))}$. In total we have $L \cdot 2^{O(1 / \delta \log (1 / \delta))}$ plus $(L+1) \cdot\left(P-P^{\prime}\right)$ integral variables (not counting the fixed variables $y_{j, 0}=n_{j}$ for $j=1, \ldots, P^{\prime}$ that can be inserted directly). Since $L \leq O(1 / \delta \log (1 / \delta))$, the number of job sizes $P-P^{\prime}$ within the interval $\left[\delta(1+\delta)^{r_{L}},(1+\delta)^{r_{1}}\right]$ can be bounded also by $O(1 / \delta \log (1 / \delta))$. To see this bound calculate the number of elements $\delta(1+\delta)^{i} \in\left[\delta(1+\delta)^{r_{L}}, \delta(1+\delta)^{r_{1}}\right]$ and the number of elements $\delta(1+\delta)^{i} \in\left(\delta(1+\delta)^{r_{1}},(1+\delta)^{r_{1}}\right]$. The cardinality of the first set is $\mid\left\{i \mid(1+\delta)^{i} \in\left[(1+\delta)^{r_{L}},(1+\right.\right.$ $\left.\left.\delta)^{r_{1}}\right]\right\} \mid \leq r_{1}-r_{L}+1 \leq O(1 / \delta \log (1 / \gamma)) \leq O(1 / \delta \log (1 / \delta))$ and the cardinality of the second set is $\left|P_{1}\right| \leq O(1 / \delta \log (1 / \delta))$.

Therefore, the total number of integral variables is $2^{O(1 / \delta \log (1 / \delta))}$ and total number of linear (in-) equalities is $2 L+P-P^{\prime}+1=O(1 / \delta \log (1 / \delta))$ (not counting the constraints $x_{i}^{(\ell)} \geq 0$ and $\left.y_{j, \ell} \geq 0\right)$.


Figure 3: Scenario 2.
In scenario 2 (see also Figure 3) we do not have to consider a separate set $\mathcal{B}_{1}$ or the first $K$ bins. Clearly, here we can eliminate all variables $y_{j, 0}$. Notice that there is no job of size larger than $(1+\delta)^{r_{1}}=\bar{c}(1)=c_{\max }\left(\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right)$ (otherwise there is no feasible solution and we are done). We suppose in the following that $k_{1} \leq r_{1}$. We get immediately the following ILP:

$$
\begin{array}{lll}
\sum_{i} x_{i}^{(\ell)} & \leq m_{\ell} \quad \text { for } \ell=1, \ldots, L \\
\sum_{\ell, i} a\left(k_{j}, C_{(\ell)}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{\ell=1}^{a_{j}-1} y_{j, \ell} & =n_{j} \quad \text { for } j=1, \ldots, P \\
\sum_{i} \operatorname{size}\left(C_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{j: a_{j}>\ell} y_{j, \ell} \delta(1+\delta)^{k_{j}} & \leq m_{\ell} \bar{c}(\ell) & \text { for } \ell=1, \ldots, L \\
x_{i}^{(\ell)} \text { integral } \geq 0 \quad \text { for } \ell=1, \ldots, L \text { and } i=1, \ldots, h_{\ell} & & \\
y_{j, \ell} \text { integral } \geq 0 \quad \text { for } j=1, \ldots, P \text { and } \ell=1, \ldots, a_{j}-1 & &
\end{array}
$$

Here the largest capacity divided by the smallest capacity $c_{\max }\left(\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right) / c_{\min }\left(\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right)$ is bounded by $O\left((K-1)(\delta+1) /\left(\gamma \delta^{2}\right)\right)=O\left(K /\left(\gamma \delta^{2}\right)\right)=O\left(1 / \delta^{5} \log (1 / \delta)\right)$ using $K=O(1 / \delta \log (1 / \delta))$ and $\gamma=\Theta\left(\delta^{2}\right)$. This implies that $(1+\delta)^{r_{1}-r_{L}} \leq O\left(1 / \delta^{5} \log (1 / \delta)\right), r_{1}-r_{L} \leq O(1 / \delta \log (1 / \delta))$ and $L \leq r_{1}-r_{L}+1 \leq O(1 / \delta \log (1 / \delta))$. The number of job sizes with values in $\left(\delta(1+\delta)^{r_{L}},(1+\delta)^{r_{1}}\right]$ is also bounded by $|P| \leq O(1 / \delta \log (1 / \delta))$. This implies that the number of integral variables is $2^{O(1 / \delta \log (1 / \delta))}$ and that the number of inequalities is $O(1 / \delta \log (1 / \delta))$.

### 3.2 How to solve the ILP?

The natural way to solve the ILP with a constant number of variables is to use the classical algorithm by Lenstra [28]. This approach was also mentioned by Hochbaum and Shmoys [22] and Alon et al [1] for scheduling on identical machines. This would give running time $d^{O\left(d^{2}\right)} s=2^{O\left(d^{2} \log (d)\right)} s$ where the dimension $d=2^{O(1 / \delta \log (1 / \delta))}$ and $s$ is the length of the input. Therefore, the running time can be bounded by $2^{2^{O\left(1 / \delta^{2}(\log (1 / \delta))^{2}\right)}} s$ - doubly exponential in $1 / \delta$. A better way is to use the algorithm by Kannan [27] with running time $d^{O(d)} s$ and to use a nice result by Eisenbrand and Shmonin [9] about integer cones

$$
\text { int }-\operatorname{cone}(X)=\left\{\lambda_{1} x_{1}+\ldots+\lambda_{t} x_{t} \mid t \geq 0 ; x_{1}, \ldots, x_{t} \in X ; \lambda_{1}, \ldots, \lambda_{t} \in \mathbb{Z}_{\geq 0}\right\}
$$

where $X \subset \mathbb{R}^{m}$ is a finite set and $m$ corresponds to the number of constraints.
Theorem 3.1 [9] Let $X \subset \mathbb{Z}^{m}$ be a finite set of integer vectors and let $b \in \operatorname{int}-\operatorname{cone}(X)$. Then there exists a subset $\tilde{X} \subset X$ such that $b \in$ int $-\operatorname{cone}(\tilde{X})$ and $|\tilde{X}| \leq 2 m \log (4 m M)$ where $M=$ $\max _{x \in X}\|x\|_{\infty}$.

In our context $t$ corresponds to the number of variables, $\lambda_{i}$ to the variables and $x_{i}$ to the vectors with the coefficients of the variables. In the following we show how to apply this result for our $\left(x_{i}^{(\ell)}\right)$ variables. To do this we need integer coefficients with small size. The first $L+P-P^{\prime}$ constraints have already this form and the values $a\left(k_{j}, C_{i}^{(\ell)}\right)$ are bounded by $1 / \delta$. We round now the values size $\left(C_{i}^{(\ell)}\right)$ up to the next multiple of $\delta^{2}(1+\delta)^{r_{\ell}}=\delta^{2} \bar{c}(\ell)$. The rounded value $\operatorname{size}^{\prime}\left(C_{i}^{(\ell)}\right) \leq \operatorname{size}\left(C_{i}^{(\ell)}\right)(1+\delta)$ using $\delta \bar{c}(\ell) \leq \operatorname{size}\left(C_{i}^{(\ell)}\right)$. Therefore, a feasible solution of our original ILP satisfies

$$
\sum_{i} \operatorname{size}^{\prime}\left(C_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{j: a_{j}>\ell} y_{j, \ell} \delta(1+\delta)^{k_{j}} \leq m_{\ell} \bar{c}(\ell)(1+\delta)
$$

Furthermore, let us divide the $L$ constraints above by $\delta^{2} \bar{c}(\ell)(\ell=1, \ldots, L)$. Then, the coefficients of $x_{i}^{(\ell)}$ are now $\operatorname{size}^{\prime}\left(C_{i}^{(\ell)}\right) /\left(\delta^{2} \bar{c}(\ell)\right)=a_{i, \ell} \delta^{2} \bar{c}(\ell) / \delta^{2} \bar{c}(\ell)=a_{i, \ell} \in\left\{1 / \delta, \ldots, 1 / \delta^{2}+1 / \delta\right\}$. Using our assumption that $1 / \delta$ is integral, the coefficients are also integral and bounded by $2 / \delta^{2}$.

Notice that increasing the capacity of all bins and dividing all coefficients as above implies also a feasible solution for the modified ILP. Now let us consider a feasible solution for the modified ILP. Considering only the $x_{i}^{(\ell)}$ variables we obtain the following system of equalities:

$$
\begin{array}{lll}
\sum_{i} x_{i}^{(\ell)} & =\bar{m}_{\ell} & \text { for } \ell=1, \ldots, L \\
\sum_{\ell, i} a\left(k_{j}, C_{i}^{(\ell)}\right) x_{i}^{(\ell)} & =\bar{n}_{j} & \text { for } j=P^{\prime}+1, \ldots, P \\
\sum_{i} \frac{s i z z^{\prime}\left(C_{i}^{(\ell)}\right)}{\delta^{2}(\ell)} x_{i}^{(\ell)} & =\text { Area( } \ell, \text { large }) & \text { for } \ell=1, \ldots, L
\end{array}
$$

where the values $\bar{m}_{\ell}, \bar{n}_{j}$ and Area( $\ell$, large) are given by the feasible solution. Then, the result by Eisenbrand and Shmonin [9] implies that there is an integral solution of this system with at most $2 m \log (4 m M) \leq 2\left(2 L+P-P^{\prime}\right) \log \left(4\left(2 L+P-P^{\prime}\right) 2 / \delta^{2}\right) \leq O\left(1 / \delta(\log (1 / \delta))^{2}\right)$ many integral variables with values larger than zero (using $m=2 L+P-P^{\prime}$, and $L, P-P^{\prime} \leq$ $O(1 / \delta \log (1 / \delta))$ and $\left.\max _{x \in X}\|x\| \leq 2 / \delta^{2}\right)$. Therefore, a feasible solution for the modified ILP contains only $O\left(1 / \delta(\log (1 / \delta))^{2}\right)$ many integral nonzero variables $x_{i}^{(\ell)}>0$. By enumeration we can choose a subset of size $O\left(1 / \delta\left(\log (1 / \delta)^{2}\right)\right.$, set the other $x_{i}^{(\ell)}$ variables equal to 0 and solve the smaller ILP instance with the polynomial number of variables. The number of remaining variables in the small ILP is bounded by $(L+1)\left(P-P^{\prime}\right)+O\left(1 / \delta(\log (1 / \delta))^{2}\right)=O\left(1 / \delta^{2}(\log (1 / \delta))^{2}\right)$. This implies the following result.

Lemma 3.3 If there is a feasible solution for the original ILP, then there is at least one small ILP instance with a feasible solution. The number of variables in each small ILP instance is $O\left(1 / \delta^{2} \log (1 / \delta)^{2}\right)$.

The number of choices or small ILP instances is bounded by

$$
\binom{2^{O(1 / \delta \log (1 / \delta))}}{O\left(1 / \delta(\log (1 / \delta))^{2}\right)} \leq 2^{O\left(1 / \delta^{2}(\log (1 / \delta))^{3}\right)}
$$

The small ILP has still non-integral coefficients and the running time to solve an ILP depends also on the size $s$ of the input. Therefore, we will modify the small ILP a second time. We round up the coefficients size ${ }^{\prime}\left(C_{i}^{(\ell)}\right)$ and $\delta(1+\delta)^{k_{j}}$ to the next multiple of $\delta^{2}(1+\delta)^{r_{L}}$. Let $\overline{\operatorname{size}}\left(C_{i}^{(\ell)}\right)=\bar{a}_{i, \ell} \delta^{2}(1+\delta)^{r_{L}}$ be the rounded value for the configuration $C_{i}^{(\ell)}$ and $\bar{b}_{j} \delta^{2}(1+\delta)^{r_{L}}$ be the rounded value for the processing time $\delta(1+\delta)^{k_{j}}$. Since $\delta(1+\delta)^{k_{j}}$ and size ${ }^{\prime}\left(C_{i}^{(\ell)}\right)$ are both larger than $\delta(1+\delta)^{r_{L}}$, we can replace the inequalities

$$
\sum_{i} \operatorname{size}^{\prime}\left(C_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{j} y_{j, \ell} \delta(1+\delta)^{k_{j}} \leq m_{\ell} \bar{c}(\ell)(1+\delta)
$$

by

$$
\sum_{i} \bar{a}_{i, \ell} \delta^{2}(1+\delta)^{r_{L}} x_{i}^{(\ell)}+\sum_{j} \bar{b}_{j} \delta^{2}(1+\delta)^{r_{L}} y_{j, \ell} \leq m_{\ell} \bar{c}(\ell)(1+\delta)^{2} .
$$

Dividing the inequalities by $\delta^{2}(1+\delta)^{r_{L}}$, the coefficients

$$
\bar{a}_{i, \ell} \leq \frac{(1+\delta)^{r_{\ell}+2}}{\delta^{2}(1+\delta)^{r_{L}}}+1 \leq \frac{1}{\gamma} \frac{(1+\delta)^{2}}{\delta^{2}}+1 \leq O\left(\frac{1}{\delta^{4}}\right)
$$

and

$$
\bar{b}_{j} \leq \frac{\delta(1+\delta)^{r_{1}}}{\delta^{2}(1+\delta)^{r_{L}}}+1 \leq \frac{1}{\gamma} \frac{1}{\delta}+1 \leq O\left(\frac{1}{\delta^{3}}\right) .
$$

Above we have used that $(1+\delta)^{r_{1}} /(1+\delta)^{r_{L}}=c_{\max }\left(\mathcal{B}_{2}\right) / c_{\min }\left(\mathcal{B}_{2}\right) \leq 1 / \gamma$. The same modification can be used for the area constraint $\sum_{j=1}^{P} y_{j, 0} \delta(1+\delta)^{k_{j}} \leq S_{0}$ with new right hand side $S_{0}^{\text {new }}$ (here we round the coefficients also to a multiple $\bar{b}_{j}$ of $\delta^{2}(1+\delta)^{r_{L}}$, and set $\left.C=\sum_{j=1}^{P^{\prime}} y_{j, 0} \delta(1+\delta)^{k_{j}}\right)$. The new constraint is $\sum_{j=P^{\prime}+1}^{P} y_{j, 0} \bar{b}_{j} \delta^{2}(1+\delta)^{r_{L}}+C \leq S_{0}^{\text {new }}$. In this case, we have to increase also the free space $S_{0}$ to $S_{0}(1+\delta)$. By increasing the capacities of the first $K^{\prime}$ bins, the new free space $S_{0}^{\text {new }}=\sum_{i=1}^{K^{\prime}} \bar{c}_{i}(1+\delta)^{2}-\sum_{j=1}^{H} \bar{p}_{j} \geq S_{0}(1+\delta)$. Then, the old inequality $\sum_{j=P^{\prime}+1}^{P} y_{j, 0} \delta(1+\delta)^{k_{j}}+C \leq S_{0}$ implies the constraint with the rounded coefficients and right hand side $S_{0}^{\text {new }}$. Here we use that $\delta(1+\delta)^{k_{j}} \geq \delta \bar{c}(L)=\delta(1+\delta)^{r_{L}}$ (otherwise the job would be tiny) and that the rounding error for each job $\delta^{2}(1+\delta)^{r_{L}}$ is at most a $\delta$-fraction of its processing time. In addition the coefficients $\bar{b}_{j} \delta^{2}(1+\delta)^{r_{L}}$ divided by $\delta^{2}(1+\delta)^{r_{L}}$ can be bounded by $O\left(1 / \gamma \cdot 1 / \delta^{2}\right)=O\left(1 / \delta^{4}\right)$. Furthermore notice that we can round down the right hand sides to the next integer values. Therefore we obtain the following statement.

Lemma 3.4 If there is a feasible solution of the original ILP (with bin capacities $\bar{c}(\ell)$ ), then there is also a feasible solution of at least one modified small ILP instance with the following constraints:

$$
\begin{array}{lll}
\sum_{i} x_{i}^{(\ell)} & \leq m_{\ell} & \text { for } \ell=1, \ldots, L \\
\sum_{\ell, i} a\left(k_{j}, C_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{\ell=0}^{a_{j}-1} y_{j, \ell} & =n_{j} & \text { for } j=P^{\prime}+1, \ldots, P \\
\sum_{i} \bar{a}_{i, \ell} x_{i}^{(\ell)}+\sum_{j: \ell<a_{j}} \bar{b}_{j} y_{j, \ell} & \leq\left\lfloor\frac{m_{\ell} \bar{c}(\ell)(1+\delta)^{2}}{\delta^{2} \bar{c}(L)}\right\rfloor & \text { for } \ell=1, \ldots, L \\
\sum_{j=P^{\prime}+1}^{P} \bar{b}_{j} y_{j, 0} & \leq\left\lfloor\frac{\left(S_{0}^{\text {eew }}-C\right)}{\delta^{2} \bar{c}(L)}\right\rfloor &
\end{array}
$$

The ILP instance has only $O\left(1 / \delta^{2} \log (1 / \delta)^{2}\right)$ integral variables $\left(x_{i}^{(\ell)}, y_{j, \ell}\right)$ with coefficients bounded by $O\left(1 / \delta^{4}\right)$.

Notice that we have increased the capacities of the bins in group $B_{\ell}$ from $\bar{c}(\ell)$ to now $\bar{c}(\ell)(1+\delta)^{2}$ (for $\ell \geq 1$ ) and the bins $b_{i}$ in group $B_{0}$ from $\bar{c}_{i}$ to $\bar{c}_{i}(1+\delta)^{2}$ for $i=1, \ldots, K^{\prime}$.

Let us consider the right hand sides of the inequalities more carefully. Notice that the values can be reduced to $O\left(1 / \delta^{4}\left[\sum_{i} x_{i}^{(\ell)}+\sum_{j} y_{j, \ell}\right]\right) \leq O\left(1 / \delta^{4}\left[m_{\ell}+\sum_{j} n_{j}\right]\right) \leq O\left(n / \delta^{4}\right)$ and $O\left(1 / \delta^{4} \sum_{j} y_{j, 0}\right) \leq$ $O\left(n / \delta^{4}\right)$, respectively. Therefore, the length $s$ of the ILP instance can be bounded by poly $(1 / \delta) \log (n)$ and the dimension $d=O\left(1 / \delta^{2} \log (1 / \delta)^{2}\right)$. Using the algorithm by Kannan [27] the running time to solve one ILP instance is at most $d^{O(d)} s \leq 2^{O\left(1 / \delta^{2}(\log (1 / \delta))^{3}\right)} \log (n)$. Over all choices of integral variables, the overall running time for scenario 1 and 2 is bounded by $2^{O\left(1 / \delta^{2}(\log (1 / \delta))^{3}\right)} \log (n)+O(n) \leq$ $2^{O\left(1 / \delta^{2}(\log (1 / \delta))^{3}\right)}+$ poly $(n)$.

The algorithm for scenario 1 works as follows:
given: bin set $\mathcal{B}_{1}^{\prime}=\left\{b_{1}, \ldots, b_{K^{\prime}}\right\}$ and $\mathcal{B}_{2}=\left\{b_{K+1}, \ldots, b_{m}\right\}$.
(0) if $\sum_{j=1}^{n} \bar{p}_{j}>\sum_{i=1}^{m} \bar{c}_{i}$ then assert that there is no solution for the makespan and stop.
(1) remove the tiny jobs with size $\leq \delta \bar{c}_{m}$ and try to pack the huge jobs with size $>\delta \bar{c}_{K^{\prime}}$ into the first $K^{\prime}$ enlarged bins.
(2) if there is a feasible packing for the huge jobs into the enlarged $K^{\prime}$ bins then
(2.1) for each choice with $O\left(1 / \delta \log (1 / \delta)^{2}\right)$ integral $x_{i}^{(\ell)}$ - variables
(2.1.1) set up the modified small ILP with bounded coefficients,
(2.1.2) apply the algorithm by Kannan to the ILP instance and store a solution (if there is any),


Figure 4: Packing jobs using $x_{i}^{(\ell)}$ variables.
(2.2) if there is at least one feasible solution $(\bar{x}, \bar{y})$ then
(2.2.1) pack the large and small jobs according to the solution $(\bar{x}, \bar{y})$ into the enlarged bins,
(2.2.2) place the tiny jobs into the free space of the enlarged bins,
(2.2.3) assert that there is a solution with the approximate makespan (and output the corresponding packing).
otherwise assert that there is no solution for the makespan.
otherwise assert that there is no solution for the makespan.
If there is a schedule of length $T$, then there is at least one modified ILP instance with a feasible solution $(\bar{x}, \bar{y})$. The capacities in this modified ILP are $\bar{c}^{\prime}(\ell)=\bar{c}(\ell)(1+\delta)^{2}$ for each block $B_{\ell}$ and $\bar{c}_{i}^{\prime}=\bar{c}_{i}(1+\delta)^{2}$ for $i=1, \ldots, K^{\prime}$ (in $\mathcal{B}_{1}^{\prime}$ ). In the first phase of our algorithm we pack the huge jobs into bins of size $\bar{c}_{i}(1+\delta)$. Then, according to the feasible ILP solution we pack first the jobs via the $\bar{x}_{i}^{(\ell)}$ values into the bins of block $B_{\ell}$ (see Figure 4). Then using the $\bar{y}_{j, \ell}$ values we place jobs as small ones into the corresponding bins that are enlarged here from $\bar{c}^{\prime}(\ell)$ to $\bar{c}^{\prime}(\ell)(1+\delta)$. Finally we pack the tiny jobs in the free space left (but here we do not enlarge the bins a second time). This is possible using the area argument. In total, this gives us a feasible packing with bin capacities $\bar{c}_{i}(1+\delta)^{3} \leq c_{i}(1+\delta)^{6}$ and a corresponding schedule of length at most $T(1+\delta)^{6} \leq O P T(1+\delta)^{7} \leq O P T(1+\epsilon)$ for $\delta \leq \epsilon / 16$ and $\epsilon \leq 1$.

In scenario 2, we do not consider the separate set $\mathcal{B}_{1}$. Here $c_{\max }\left(\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right) / c_{\min }\left(\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right)$ is at most $(1+\delta)^{r_{1}-r_{L}} \leq O\left(1 / \delta^{5} \log (1 / \delta)\right)$. On the other hand $L, P \leq O(1 / \delta \log (1 / \delta))$. The same arguments as above can be applied, only the coefficients in the second modified ILP are bounded by $1 / \delta^{2}(1+\delta)^{r_{1}+2-r_{L}} \leq O\left(1 / \delta^{7} \log (1 / \delta)\right)$.


Figure 5: Packing of small and tiny jobs.

## 4 General case with different gaps

In this section we consider now scenarios 3 and 4 (with three bin groups). First, we study scenario 3 . For the huge jobs with processing times $>\delta \bar{c}_{K^{\prime}}$ we use the same approach as in the previous section. If there is no assignment for the $H$ huge jobs into the first $K^{\prime}$ enlarged bins of group $\mathcal{B}_{1}^{\prime}$, then there is no schedule of length $T$ and we are done. Otherwise we will find a feasible approximate assignment with free space $S_{0}=\sum_{i=1}^{K^{\prime}} \bar{c}_{i}(1+\delta)-\sum_{j=1}^{H} \bar{p}_{j}$ and use now a mixed integer linear program (MILP) as described below.

### 4.1 The MILP relaxation

The set $\mathcal{B}_{2}$ contains now $m_{\ell}$ bins of size $\bar{c}(\ell)=(1+\delta)^{r_{\ell}}$ for $\ell=1, \ldots, L$ and $\mathcal{B}_{3} m_{\ell}$ bins of size $\bar{c}(\ell)=(1+\delta)^{r_{\ell}}$ for $\ell=L+1, \ldots, L+N$. Note that $\bar{c}(1)=\bar{c}_{K+1}, \bar{c}(L)=\bar{c}_{K+G}, \bar{c}(L+1)=\bar{c}_{K+G+1}$ and $\bar{c}(L+N)=\bar{c}_{m}$. Using our assumptions we have a constant number of different capacities in $\mathcal{B}_{2}, c_{\max }\left(\mathcal{B}_{2}\right) / c_{\min }\left(\mathcal{B}_{2}\right) \leq 1 / \gamma$ and a gap of $1 / \gamma$ between $c_{\min }\left(\mathcal{B}_{1}\right)$ and $c_{\max }\left(\mathcal{B}_{3}\right)$ (see also Figure 6 for an illustration). Furthermore we have $n_{j}$ jobs of size $\delta(1+\delta)^{k_{j}}$ for $j=1, \ldots, P$ (all with processing time larger than $\delta \bar{c}(L+N)=\delta(1+\delta)^{r_{L+N}}$ and smaller than or equal to $\delta \bar{c}_{K^{\prime}}$ ). Suppose (as in the other scenarios) that we have eliminated the tiny jobs $J_{\text {tiny }}$ with processing times at most $\delta(1+\delta)^{r_{L+N}}$ and that the area constraint for all jobs is satisfied (otherwise we have to increase the makespan $T$ and the corresponding bin sizes).

Similar to the ILP in the previous section we use as a configuration $C_{i}^{(\ell)}$ a multiset with numbers $\delta(1+\delta)^{j} \in\left(\delta(1+\delta)^{r_{\ell}},(1+\delta)^{r_{\ell}}\right]$ (these are the large processing times). Note that $C_{i}^{(\ell)}$ contains at most $1 / \delta$ numbers. Let $a\left(j, C_{i}^{(\ell)}\right)$ be the number of occurrences of number $\delta(1+\delta)^{j}$ in configuration $C_{i}^{(\ell)}$ and let $\operatorname{size}\left(C_{i}^{(\ell)}\right)=\sum_{j} a\left(j, C_{i}^{(\ell)}\right) \delta(1+\delta)^{j} \leq \bar{c}(\ell)$ be the total sum of the numbers in $C_{i}^{(\ell)}$. In the MILP below we use an integral or fractional variable $x_{i}^{(\ell)}$ to indicate the length of the configuration


Figure 6: Scenario 3.
$C_{i}^{(\ell)}$.
For each job size $\delta(1+\delta)^{k_{j}} \leq(1+\delta)^{r_{1}}$, let $a_{j}$ be the smallest index in $\{1, \ldots, L+N\}$ such that $\delta(1+\delta)^{k_{j}} \geq \delta(1+\delta)^{r_{a_{j}}}$. If there is no such index, then we have a tiny processing time $\delta(1+\delta)^{k_{j}}<\delta(1+\delta)^{r_{L+N}}=\delta \bar{c}_{m}$. These jobs are removed in the first step of our algorithm and will be added at the end. In addition for $j=1, \ldots, P$ and $\ell=0, \ldots, a_{j}-1$ we use variables $y_{j, \ell}$ to indicate the number of jobs of size $\delta(1+\delta)^{k_{j}}$ to be placed as a small job in group $B_{\ell}$ with bin sizes $\bar{c}(\ell)=(1+\delta)^{r_{\ell}}$. Again, $B_{0}$ is the block with the largest $K^{\prime}$ bins. Suppose that the first $P^{\prime}$ (non-huge) job sizes $(1+\delta)^{k_{j}}$ are within $\left((1+\delta)^{r_{1}}, \delta c_{K^{\prime}}\right]$. These job sizes do not fit into the bins in group $\mathcal{B}_{2} \cup \mathcal{B}_{3}$. Therefore we use for these job sizes (as in the ILP) only one variable $y_{j, 0}=n_{j}$ and set $a_{j}=0$. Furthermore, notice that each processing time for $j \geq P^{\prime}+1$ is small corresponding to $B_{0}$. We use now the following MILP:

$$
\begin{array}{rlrl}
\sum_{i} x_{i}^{(\ell)} & & \leq m_{\ell} \quad \text { for } \ell=1, \ldots, L+N \\
\sum_{\ell, i} a\left(k_{j}, C_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{\ell=0}^{a_{j}-1} y_{j, \ell} & & =n_{j} \quad \text { for } j=P^{\prime}+1, \ldots, P \\
\sum_{i} \operatorname{size}\left(C_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{j: \ell<a_{j}} y_{j, \ell} \delta(1+\delta)^{k_{j}} & \leq m_{\ell} \bar{c}(\ell) \text { for } \ell=1, \ldots, L+N \\
\sum_{j=1}^{P} y_{j, 0} \delta(1+\delta)^{k_{j}} & & \leq S_{0} \\
x_{i}^{(\ell)} \text { integral } \geq 0 & \text { for } \ell & =1, \ldots, L \text { and } i=1, \ldots, h_{\ell} \\
x_{i}^{(\ell)} \geq 0 & \text { for } \ell & =L+1, \ldots, L+N \text { and } i=1, \ldots, h_{\ell} \\
y_{j, \ell} \geq 0 & \text { for } j & =P^{\prime}+1, \ldots, P \text { and } \ell=0, \ldots, a_{j}-1 \\
y_{j, 0}=n_{j} & \text { for } j & =1, \ldots, P^{\prime}
\end{array}
$$

Interestingly, the variables $y_{j, \ell}$ (with exception of the fixed variables $y_{j, 0}=n_{j}$ for $j \leq P^{\prime}$ ) are in general fractional variables. In fact we could use the same assumption also in the other two scenarios 1 and 2 and would obtain also an MILP formulation. But then the algorithms for these scenarios are more complicated, since we have to round the corresponding values afterwards. For the MILP relaxation, we can prove the following result.

Lemma 4.1 Each feasible packing for the jobs into the bins corresponds to a feasible solution of the MILP.

Proof: First, we take out all jobs that are small corresponding to a bin. Place the huge jobs corresponding to the packing into the first block $B_{0}$. Then, the other jobs can be grouped together as configurations for each block $B_{\ell}$. Let $\tilde{x}_{i}^{(\ell)}$ be the number of bins with corresponding configuration $C_{i}^{(\ell)}$ in block $B_{\ell}$. Then, the first $L+N$ inequalities are satisfied directly. Then, let $\tilde{y}_{j, \ell}$ be the number of jobs that are packed as small jobs with size $\delta(1+\delta)^{k_{j}}$ in block $B_{\ell}$. Since all jobs are packed, the next $P-P^{\prime}$ inequalities are also satisfied. In addition, the total area of all jobs in block $B_{\ell}$ is exactly $\sum_{i} \operatorname{size}\left(C_{i}^{(\ell)}\right) \tilde{x}_{i}^{(\ell)}+\sum_{j} \tilde{y}_{j, \ell} \delta(1+\delta)^{k_{j}}$, and this clearly is bounded by the total area $m_{\ell} \bar{c}(\ell)$ of block $B_{\ell}$. Therefore, the next $L+N$ inequalities are also satisfied. The last inequality is true, since the area $\sum_{j} \tilde{y}_{j, 0} \delta(1+\delta)^{k_{j}}$ of the small jobs in $B_{0}$ must be smaller than the free space $S_{0}$.

Lemma 4.1 implies that the MILP is a relaxation of the packing problem for jobs into bins with different sizes. Notice that the feasible solution generated above has only integral values. On the other hand, we show later how to round an MILP solution to obtain a feasible packing with enlarged capacities.

Lemma 4.2 The number of variables in the MILP is $n^{2}+n 2^{O(1 / \delta \log (1 / \delta))}$, the number of integral variables is at most $2^{O(1 / \delta \log (1 / \delta))}$, and the number of constraints (not counting the non-negativity constraints) is at most $O(n)$.

Proof: The number of configurations per block $B_{\ell}$ is again bounded by $2^{O(1 / \delta \log (1 / \delta))}$. The number $L$ is bounded by $O(1 / \delta \log (1 / \gamma))=O(1 / \delta \log (1 / \delta))$ using that $c_{\max }\left(\mathcal{B}_{2}\right) / c_{\min }\left(\mathcal{B}_{2}\right)$ is at most $1 / \gamma$ and $\gamma=\Theta\left(\delta^{2}\right)$. Thus, the number of integral variables is at most $2^{O(1 / \delta \log (1 / \delta))}$. Since the number $m$ of machines is bounded by the number $n$ of jobs, the number of blocks including $B_{0}$ is $L+N+1 \leq$ $n$ and number of job sizes $P \leq n$. This implies that the total number of variables is at most $n^{2}+n 2^{O(1 / \delta \log (1 / \delta))}$ and that the number of constraints is at most $O(n)$.


Figure 7: Scenario 4.
In scenario 4 , the set $\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}$ (and also $\left.\mathcal{B}_{1} \cup \mathcal{B}_{2}\right)$ has a constant range of capacities, i.e. $c_{\max }\left(\mathcal{B}_{1}^{\prime} \cup\right.$ $\left.\mathcal{B}_{2}\right) / c_{\text {min }}\left(\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}\right) \leq(K-1)(\delta+1) /\left(\gamma \delta^{2}\right)$. Furthermore, there is a gap of $1 / \gamma$ between $c_{\text {min }}\left(\mathcal{B}_{1}\right)$ and
$c_{\text {max }}\left(\mathcal{B}_{3}\right)$. Therefore we can use a similar approach as in scenario 3 with blocks $B_{1}, \ldots, B_{L}$ within $\mathcal{B}_{1} \cup \mathcal{B}_{2}$. Here we obtain an MILP with integral configuration variables for $\mathcal{B}_{1} \cup \mathcal{B}_{2}$ and fractional configuration variables for $\mathcal{B}_{3}$. The number of integral variables here is again $2^{O(1 / \delta \log (1 / \delta))}$, and the value $L \leq O\left(1 / \delta \log \left((K-1) /\left(\gamma \delta^{2}\right)\right)\right)=O(1 / \delta \log (1 / \delta))$. As above the number of constraints is at most $O(n)$ and the number of all variables is at most $n^{2}+n 2^{O(1 / \delta \log (1 / \delta))}$.

### 4.2 How to solve the MILP?

For the MILP we use the same argument via the integer cone for the $\left(x_{i}^{(\ell)}\right)$ variables. In addition we round the sizes or processing times of large items or jobs to solve later the corresponding LP in the underlying algorithm of Lenstra and Kannan more efficiently. Each large size $\delta(1+\delta)^{k_{j}} \in C_{i}^{(\ell)}$ is rounded up to the next multiple of $\delta^{2}(1+\delta)^{r_{\ell}}$ for $\ell=1, \ldots, L$. Let $\operatorname{round}_{\ell}\left[\delta(1+\delta)^{k_{j}}\right]$ be the rounded number in block $B_{\ell}$. This generates also modified configurations with total size at most $\bar{c}(\ell)(1+\delta)=(1+\delta)^{r_{\ell}+1}$, since at most $1 / \delta$ items in each configuration are rounded up. Notice that rounding up different numbers $\delta(1+\delta)^{i} \in\left(\delta(1+\delta)^{r_{\ell}},(1+\delta)^{r_{\ell}}\right]$ up to round $_{\ell}\left[\delta(1+\delta)^{i}\right]$ generates different rounded numbers. Suppose by contradiction that two rounded numbers are equal $\operatorname{round}_{\ell}\left[\delta(1+\delta)^{i+1}\right]=\operatorname{round}_{\ell}\left[\delta(1+\delta)^{i}\right]$. Then the distance between the original numbers $\delta(1+\delta)^{i+1}-\delta(1+\delta)^{i}=\delta^{2}(1+\delta)^{i}$ is at most $\delta^{2}(1+\delta)^{r_{\ell}}$, and this is possible only if $i \leq r_{\ell}$. But this is a contradiction, since $i$ should be larger than $r_{\ell}$.

Let $\bar{C}_{1}^{(\ell)}, \ldots, \bar{C}_{\bar{h}_{\ell}}^{(\ell)}$ be the sequence of all configuration or partitions of $\bar{c}(\ell)(1+\delta)$ into the rounded numbers $\left\{\right.$ round $\left._{\ell}\left[\delta(1+\delta)^{k_{j}}\right] \mid \delta(1+\delta)^{k_{j}} \in\left(\delta(1+\delta)^{r_{\ell}},(1+\delta)^{r_{\ell}}\right]\right\}$. Then, the equality for each job size $j \in\left\{P^{\prime}+1, \ldots, P\right\}$ has now the form

$$
\sum_{\ell, i: \text { round }\left[\delta(1+\delta)^{\left.k_{j}\right]} \in \in \bar{C}_{i}^{(\ell)}\right.} a\left(k_{j}, \bar{C}_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{\ell=0}^{a_{j}-1} y_{j, \ell}=n_{j},
$$

where $a\left(k_{j}, \bar{C}_{i}^{(\ell)}\right)$ is the number of occurrences of the rounded value $\operatorname{round}\left[\delta(1+\delta)^{k_{j}}\right]$ in $\bar{C}_{i}^{(\ell)}$. In addition we have as new constraints

$$
\sum_{i} \operatorname{size}\left(\bar{C}_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{j} y_{j, \ell} \delta(1+\delta)^{k_{j}} \leq m_{\ell} \bar{c}(\ell)(1+\delta)
$$

for $\ell=1, \ldots, L$ and

$$
\sum_{j=1}^{P} y_{j, 0} \delta(1+\delta)^{k_{j}} \leq S_{0}
$$

Clearly, if there is a feasible solution for the original MILP, then there is also a feasible solution for the MILP with modified coefficients. Now, the values size $\left(\bar{C}_{i}^{(\ell)}\right)$ are multiples of $\delta^{2}(1+\delta)^{r_{\ell}}$ and bounded by $(1+\delta)^{r_{\ell}+1}$. By dividing the corresponding constraints by $\delta^{2}(1+\delta)^{r_{\ell}}$, the coefficients of $x_{i}^{(\ell)}$ are again integral and bounded by $2 / \delta^{2}$. Therefore, using the same argument as for the ILP (with a system of equalities for the $\left(x_{i}^{(\ell)}\right)$ variables) each feasible integral solution of MILP has at most $O\left(1 / \delta(\log (1 / \delta))^{2}\right)$ integral variables with values larger than zero. Let $P\left(\mathcal{B}_{2}\right)$ be indices of the large job sizes corresponding to a block $B_{\ell} \in \mathcal{B}_{2}$ (i.e. $P\left(\mathcal{B}_{2}\right)=\left\{j \mid \delta(1+\delta)^{k_{j}} \in\left(\delta(1+\delta)^{r_{L}},(1+\delta)^{r_{1}}\right]\right\}$ ). The cardinality of $P\left(\mathcal{B}_{2}\right)$ can be bounded by $O(1 / \delta \log (1 / \delta))$ (see also Lemma 3.2).

To prove the bound for the number of integral variables consider for the $x_{i}^{(\ell)}$ variables of the
blocks $B_{\ell} \in \mathcal{B}_{2}$ the following system of equalities:

$$
\begin{array}{lll}
\sum_{i} x_{i}^{(\ell)} & =\bar{m}_{\ell} & \text { for } \ell=1, \ldots, L \\
\sum_{\ell, i} a\left(k_{j}, \bar{C}_{i}^{(\ell)}\right) x_{i}^{(\ell)} & =\bar{n}_{j} & \\
\text { for } j \in P\left(\mathcal{B}_{2}\right) \\
\sum_{i} \frac{\operatorname{size}\left(\bar{C}_{i}^{(\ell)}\right)}{\delta^{2}(\bar{c}(\ell)} x_{i}^{(\ell)} & =\text { Area( } \ell, \text { large }) & \text { for } \ell=1, \ldots, L,
\end{array}
$$

where the values $\bar{m}_{\ell}, \bar{n}_{j}$ and Area( $\ell$, large) are given by the feasible solution. Then, the result by Eisenbrand and Shmonin [9] implies that there is an integral solution of this system with at most $2 m \log (4 m M)=2\left(2 L+\left|P\left(\mathcal{B}_{2}\right)\right|\right) \log \left(4\left(2 L+\left|P\left(\mathcal{B}_{2}\right)\right|\right) 2 / \delta^{2}\right) \leq O\left(1 / \delta(\log (1 / \delta))^{2}\right)$ integral variables with values larger than zero (using $m=2 L+\left|P\left(\mathcal{B}_{2}\right)\right|$, and $L,\left|P\left(\mathcal{B}_{2}\right)\right| \leq O(1 / \delta \log (1 / \delta))$ and $\max _{x \in X}\|x\| \leq 2 / \delta^{2}$ ). Therefore, a feasible solution of the modified MILP contains only $O\left(1 / \delta(\log (1 / \delta))^{2}\right)$ integral nonzero variables $x_{i}^{(\ell)}>0$ with $\ell \in\{1, \ldots, L\}$.

For each choice with $O\left(1 / \delta(\log (1+\delta))^{2}\right)$ such variables, we obtain a restricted MILP instance with only few integral variables. The number of choices or small instances is again bounded by

$$
\binom{2^{O(1 / \delta \log (1 / \delta))}}{O\left(1 / \delta(\log (1 / \delta))^{2}\right)} \leq 2^{O\left(1 / \delta^{2} \log (1 / \delta)^{3}\right)}
$$

Lemma 4.3 If there is a feasible solution for the original MILP, then there is a feasible solution for at least one of the restricted MILP instances with modified coefficients. The number of instances is $2^{O\left(1 / \delta^{2} \log (1 / \delta)^{3}\right)}$ and the number of integral variables in each MILP instance is at most $O\left(1 / \delta \log (1 / \delta)^{2}\right)$.

In order to solve such MILP instances, we round the coefficients a second time (similar to what we did to the ILP). We round here the coefficient $\operatorname{size}\left(\bar{C}_{i}^{(\ell)}\right)$ for $\ell=1, \ldots, L$, size $\left(C_{i}^{(\ell)}\right)$ for $\ell=L+1, \ldots, L+N$ and the values $\delta(1+\delta)^{k_{j}}$ for bin group $B_{\ell}$ to next multiple of $\delta /(2 n)(1+\delta)^{r_{\ell}}$, i.e. to $\bar{a}_{i, \ell} \delta /(2 n)(1+\delta)^{r_{\ell}}$ and to $\bar{b}_{j, \ell} \delta /(2 n)(1+\delta)^{r_{\ell}}$. Since $\sum_{i} x_{i}^{(\ell)} \leq m_{\ell} \leq n$ and $\sum_{j} y_{j, \ell} \leq \sum_{j} n_{j} \leq n$, a feasible solution of $\sum_{i} \operatorname{size}\left(\bar{C}_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{j} \delta(1+\delta)^{k_{j}} y_{j, \ell} \leq m_{\ell} \bar{c}(\ell)(1+\delta)$ implies a solution of the form $\sum_{i} \bar{a}_{i, \ell} \delta /(2 n)(1+\delta)^{r} x_{i}^{(\ell)}+\sum_{j} \bar{b}_{j, \ell} \delta /(2 n)(1+\delta)^{r} \ell y_{j, \ell} \leq m_{\ell} \bar{c}(\ell)(1+2 \delta)$ for $\ell=1, \ldots, L$. A similar implication can be proved for the inequalities corresponding to the groups $B_{\ell}$ for $\ell=L+1, \ldots, L+N$. Here we have to increase the bin capacities to $\bar{c}(\ell)(1+2 \delta)$ for $\ell=1, \ldots, L+N$.

For the area constraint with $S_{0}$ we round the coefficients of $y_{j, 0}$ (for $j \geq P^{\prime}+1$ ) to the next multiples of $\delta /(2 n)(1+\delta)^{r_{1}}$. Then, a feasible solution of

$$
\sum_{j=P^{\prime}+1}^{P} \delta(1+\delta)^{k_{j}} y_{j, 0} \leq \bar{S}_{0}
$$

with $\bar{S}_{0}=\left(S_{0}-\sum_{j=1}^{P^{\prime}} n_{j} \delta(1+\delta)^{k_{j}}\right)$ implies

$$
(\delta /(2 n))(1+\delta)^{r_{1}} \sum_{j=P^{\prime}+1}^{P} \bar{b}_{j, 0} y_{j, 0} \leq \bar{S}_{0}+(n) \delta /(2 n)(1+\delta)^{r_{1}} \leq \bar{S}_{0}+(\delta / 2) \bar{c}(1) .
$$

By increasing the capacities of the first $K^{\prime}$ bins to $\bar{c}_{i}(1+\delta)^{2}$, the free space $S_{0}=\sum_{i=1}^{K^{\prime}} \bar{c}_{i}(1+\delta)-$ $\sum_{j=1}^{H} \bar{p}_{j}$ can be enlarged to $S_{0}^{\text {new }}=\sum_{i=1}^{K^{\prime}} \bar{c}_{i}(1+\delta)^{2}-\sum_{j=1}^{H} \bar{p}_{j}=S_{0}+\sum_{i=1}^{K^{\prime}} \bar{c}_{i}\left(\delta+\delta^{2}\right) \geq S_{0}+\delta \bar{c}_{K^{\prime}} \geq$ $S_{0}+\delta \bar{c}(1)$. Here we have to increase the capacities to $\bar{c}_{i}^{\prime}=\bar{c}_{i}(1+3 \delta) \geq \bar{c}_{i}(1+\delta)^{2}$ for $i=1, \ldots, K^{\prime}$. This implies that $\bar{S}_{0}^{\text {new }}=\left(S_{0}^{\text {new }}-\sum_{j=1}^{P^{\prime}} n_{j} \delta(1+\delta)^{k_{j}}\right) \geq \bar{S}_{0}+\delta \bar{c}(1)$.

Finally, after dividing the constraints above by $\delta /(2 n)(1+\delta)^{r_{\ell}}$ and $\delta /(2 n)(1+\delta)^{r_{1}}$, the coefficients $\bar{a}_{i, \ell}$ and $\bar{b}_{j, \ell}$ are all integral and bounded by $O(n / \delta)$ for $j \geq P^{\prime}+1$. To see this we use that the rounded values

$$
\begin{array}{lll}
\bar{a}_{i, \ell} \delta /(2 n)(1+\delta)^{r_{\ell}} & \leq \bar{c}(\ell)(1+2 \delta)=(1+\delta)^{r_{\ell}}(1+2 \delta) & \text { for } \ell=1, \ldots, L+N \\
\bar{b}_{j, \ell} \delta /(2 n)(1+\delta)^{r_{\ell}} & \leq \delta \bar{c}(\ell)=\delta(1+\delta)^{r_{\ell}} & \text { for } \ell=1, \ldots, L+N \\
\bar{b}_{j, 0} \delta /(2 n)(1+\delta)^{r_{1}} & \leq \bar{c}(1)=(1+\delta)^{r_{1}} & \text { for } \ell=0 .
\end{array}
$$

Here we use also the fact that the $y_{j, 0}$ variables are replaced by their fixed values $n_{j}$ for $j=$ $1, \ldots, P^{\prime}$ and that their coefficients are not rounded. Furthermore notice that we can round down the right hand sides of the inequalities to the next integer value. For each choice of $O\left(1 / \delta(\log (1 / \delta))^{2}\right)$ integral variables we have now to solve a small modified MILP instance.

Lemma 4.4 If a restricted MILP instance has a feasible solution, then the modified MILP with the following constraints has also a feasible solution.

$$
\begin{array}{lll}
\sum_{i} x_{i}^{(\ell)} & \leq m_{\ell} & \text { for } \ell=1, \ldots, L+N \\
\sum_{\ell, i} a\left(k_{j}, \bar{C}_{i}^{(\ell)}\right) x_{i}^{(\ell)}+\sum_{\ell=0}^{a_{j}-1} y_{j, \ell} & =n_{j} & \text { for } j=P^{\prime}+1, \ldots, P \\
\sum_{i} \bar{a}_{i, \ell} x_{i}^{(\ell)}+\sum_{j: \ell<a_{j}} \bar{b}_{j, \ell} y_{j, \ell} & \leq\left\lfloor\frac{m_{\ell}(1+2 \delta)(2 n)}{\delta \delta}\right\rfloor & \text { for } \ell=1, \ldots, L+N \\
\sum_{j=P^{\prime}+1}^{P} \bar{b}_{j, 0} y_{j, 0} & \leq\left\lfloor\frac{\bar{S}_{0}^{\text {new }}(2 n)}{\delta \bar{\delta}(1)}\right\rfloor . &
\end{array}
$$

The new MILP has $d=O\left(1 / \delta \log (1 / \delta)^{2}\right)$ integral variables, at most $n^{2}+n 2^{O(1 / \delta \log (1 / \delta))}$ fractional variables, $O(n)$ constraints (not counting the constraints $x_{i}^{(\ell)} \geq 0$ and $y_{j, \ell} \geq 0$ ), and coefficients bounded by $O(n / \delta)$.

Let us consider the right hand sides more carefully. Notice that the values $m_{\ell}(1+2 \delta)(2 n) / \delta \leq$ $O\left(n^{2} / \delta\right)$ and $\sum_{j} \bar{b}_{j, 0} y_{j, 0} \leq(2 n / \delta) \sum_{j} y_{j, 0} \leq 2 n^{2} / \delta$. Therefore, the length $s$ of the MILP instance can be bounded roughly by $\left(n^{2}+n 2^{O(1 / \delta \log (1 / \delta))}\right) n \log (n / \delta)=$ poly $(n, 1 / \delta)+n^{2} \log (n) 2^{O(1 / \delta \log (1 / \delta))}$. Using further arguments about the $x_{i}^{(\ell)}$ variables, the length $s$ can be bounded also by poly $(n, 1 / \delta)+$ $n \log (n) 2^{O(1 / \delta \log (1 / \delta))}$. Kannan's algorithm [27] has running time $d^{O(d)} p o l y(s)$, where the polynomial depends on the running time to solve the underlying linear program. In our case, $d=$ $O\left(1 / \delta \log (1 / \delta)^{2}\right)$ and poly(s) can be bounded by $2^{O(1 / \delta \log (1 / \delta))}$ poly $(n)$. This implies that the total running time for one MILP instance is at most $2^{O\left(1 / \delta \log (1 / \delta)^{3}\right)}$ poly $(n)$.

Lenstra's and Kannan's algorithms [28,27] use as a subroutine an algorithm to solve a linear program with an objective function that depends only on the integral variables and a subroutine to decide whether a given vector $y \in \mathbb{R}^{d}$ belongs to the transformed set $\tau K$, where $\tau$ is a linear nonsingular transformation of $\mathbb{R}^{d}, K=\left\{\left(x_{1}, \ldots, x_{d}\right) \mid\right.$ there exist $x_{d+1}, \ldots, x_{N} \in \mathbb{R}$ such that $\left.A x \leq b\right\}$ and $N$ is the total number of variables. This decision problem above can be solved using a linear feasibility program with the $N-d$ fractional variables (see also [28]). In the following we show that the linear program above can be solved in time polynomial in $n$ and $1 / \delta$. The feasibility test can be solved in a similar way.

Lemma 4.5 The linear program with the constraints above, variables $x_{i}^{(\ell)}, y_{j, \ell} \geq 0$ and an objective function that depends only on the $d=O\left(1 / \delta \log (1 / \delta)^{2}\right)$ integral variables of the corresponding MILP can be solved in time polynomial in $n$ and $1 / \delta$.

Proof: Suppose that the $y_{j, 0}$ are replaced by their values $n_{j}$ for $j \leq P^{\prime}$. Next we insert additional positive slack variables to obtain $O(n)$ equality constraints and consider the dual linear program.

Since all variables are positive and the primal linear program has only equality constraints, we obtain dual constraints of the form $\Pi^{T} A_{j} \leq c_{j}$ with non-restricted variables $\Pi \gtrless 0$, where $c=\left(c_{1}, \ldots, c_{N}\right)$ is the objective function of the primal problem and $A_{j}$ is the $j$.th column vector of the matrix. To solve the dual and also primal linear program, let us consider the strong separation problem for the corresponding dual polyhedron $P$ : given a vector $p \in \mathbb{R}^{n}$, decide whether $p \in P$, and if not, find a hyperplane that separates $p$ from $P$, i.e. a vector $\alpha \in \mathbb{R}^{n}$ such that $\alpha^{T} p>\max \left\{\alpha^{T} x \mid x \in P\right\}$. In our case we have $O(n)$ variables and $n^{2}+n 2^{O(1 / \delta \log (1 / \delta))}$ linear constraints. First we test all dual inequalities corresponding to the primal integral variables, the primal variables $y_{\ell, j}$ and the primal slack variables. The time to check one constraint is bounded by $O(n)$. Since the number of these constraints is bounded by $O\left(n^{2}+1 / \delta(\log (1 / \delta))^{2}\right)$, this can be done in time polynomial in $n$ and $1 / \delta$. The only critical dual constraints correspond to the $x_{i}^{(\ell)}$ variables, since here we have $2^{O(1 / \delta \log (1 / \delta))}$ variables per block $B_{\ell}$. For each configuration $\bar{C}_{i}^{(\ell)}$, we have a constraint of the form

$$
\Pi_{\ell}+\sum_{j} a\left(k_{j}, \bar{C}_{i}^{(\ell)}\right) \Pi_{(L+N)+j-P^{\prime}}+\frac{\overline{s i z e}\left(C_{i}^{(\ell)}\right)}{\delta /(2 n)(1+\delta)^{r_{\ell}}} \Pi_{(L+N)+\left(P-P^{\prime}\right)+\ell} \leq 0
$$

where $\overline{\operatorname{size}}\left(C_{i}^{(\ell)}\right)$ is the rounded size of $\operatorname{size}\left(C_{i}^{(\ell)}\right)$ to the next multiple of $\delta /(2 n)(1+\delta)^{r_{\ell}}$. Notice that the right hand sides of the constraints have the same value 0 , since the objective function of the primal linear program does not depend on the corresponding variables. The separation problem for $B_{\ell}$ and vector $p$ is now (note that the $\ell$.th coefficient $p_{\ell}$ is constant over all constraints):

$$
\max _{i=1, \ldots, \bar{h}_{\ell}} \sum_{j} a\left(k_{j}, \bar{C}_{i}^{(\ell)}\right) p_{(L+N)+j-P^{\prime}}+\frac{\overline{\operatorname{size}}\left(C_{i}^{(\ell)}\right)}{\delta /(2 n)(1+\delta)^{r_{\ell}} \ell} p_{(L+N)+\left(P-P^{\prime}\right)+\ell} \leq-p_{\ell} .
$$

This is a special type of a knapsack problem with a constant number of different sizes

$$
S_{\ell}=\left\{\operatorname{round}\left[\delta(1+\delta)^{k_{j}}\right] \mid \delta(1+\delta)^{k_{j}} \in\left(\delta(1+\delta)^{r_{\ell}},(1+\delta)^{r_{\ell}}\right]\right\}
$$

Using the analysis above, $\left|S_{\ell}\right|=O(1 / \delta \log (1 / \delta))$. In our knapsack problem we have a set $I$ of items with these sizes $s_{j}$, a capacity $C=(1+\delta)^{r_{\ell}}(1+2 \delta)$ and arbitrary profits $q_{j}$. We can choose $x_{j}$ items of size $s_{j}$, but only $(1+2 \delta) / \delta$ many of them, since round $\left[\delta(1+\delta)^{k_{j}}\right] \geq \delta(1+\delta)^{r_{\ell}}$. The knapsack problem has the following form:

$$
\begin{array}{ll}
\max & \sum_{j \in I} x_{j} q_{j}+f\left(\sum_{j \in I} x_{j} s_{j}\right) q \\
\text { s.t. } & \sum_{j \in I} x_{j} s_{j} \leq C \\
& x_{j} \text { integral } \geq 0
\end{array}
$$

where $f(s)$ is the smallest multiple of $\delta /(2 n)(1+\delta)^{r_{\ell}}$ such that $f(s) \delta /(2 n)(1+\delta)^{r_{\ell}}$ is larger than $s$, and where $q_{j}$ and $q$ corresponds to $p_{(L+N)+j-P^{\prime}}$ and $p_{(L+N)+\left(P-P^{\prime}\right)+\ell}$, respectively. Since the sizes are all multiples of $\delta^{2}(1+\delta)^{r_{\ell}}$, this knapsack problem can be solved optimally by dynamic programming: storing for each number $i=1, \ldots,\left|S_{\ell}\right|$ and each size $a \in\left\{1, \ldots,(1+2 \delta) / \delta^{2}\right\}$ a maximum profitable subset (if there is any) with only the first $i$ sizes and total size $a \delta^{2}(1+\delta)^{r}$. Notice that each item size can be chosen at most $1 / \delta(1+2 \delta)=O(1 / \delta)$ times (i.e. $\left.x_{j} \in\{0, \ldots,(1+2 \delta) / \delta\}\right)$.

After $\left|S_{\ell}\right|$ iterations, we have computed a sequence of subsets $D_{1}, \ldots, D_{g}$ with maximum profit $\operatorname{profit}\left(D_{j}\right)$, where the total size size $\left(D_{j}\right)$ is a multiple of $\delta^{2}(1+\delta)^{r_{\ell}}$ for $j=1, \ldots, g$ and where $g \leq(1+2 \delta) / \delta^{2}$. Then, the best solution of our knapsack problem is one of the sets where the value $\operatorname{profit}\left(D_{i}\right)+f\left(\operatorname{size}\left(D_{i}\right)\right) q$ is maximized. The running time of the algorithm can be bounded by $O\left(\left|S_{\ell}\right| 1 / \delta^{3}\right)=O\left(1 / \delta^{4} \log (1 / \delta)\right)$.

If the profit of this subset is smaller than or equal to $-p_{\ell}$, then the corresponding vector is feasible for all $B_{\ell}$ constraints. If the profit is larger than $-p_{\ell}$, then the computed set $D_{i}$ with
maximum profit corresponds directly to the separating inequality or hyperplane. Therefore, we can solve the separation problem for $B_{\ell}$ in time polynomial in $1 / \delta$.

Since the polyhedron $P$ corresponding to the dual constraints has facet-complexity (that is the encoding of each inequality in the linear system) bounded by $O(n+1 / \delta \log (n / \delta))$ and the strong separation problem is solvable in oracle-polynomial time, the strong optimization problem for $P$ (the dual linear program) can be solved in time polynomial in $n$ and $1 / \delta$ (see [21] Theorem 6.4.9). Since the number of inequalities that are outputs of the separation oracle is bounded also by a polynomial in $n$ and $1 / \delta$, there is a polynomial time algorithm in $n$ and $1 / \delta$ that finds a basic optimal solution of the primal problem, or asserts that the primal problem is unbounded or has no solution (see [21] Lemma 6.5.15). In our case, the primal problem is always bounded. Therefore, we either obtain an optimal solution of the primal problem or know that the primal problem has no solution.

Using Kannan's algorithm for each MILP instance with $d=O\left(1 / \delta(\log (1 / \delta))^{2}\right)$ integral variables, we can compute in time $2^{O\left(1 / \delta(\log (1 / \delta))^{3}\right)}$ poly $(n)$ a feasible solution of the MILP instance or assert that there is no solution. Among all choices we obtain in $2^{O\left(1 / \delta^{2}(\log (1 / \delta))^{3}\right)}$ poly $(n)$ time a feasible solution of one of the MILP instances, if there is a schedule with makespan $T$ for the original problem. If there is such a schedule, we obtain a feasible solution $(\bar{x}, \bar{y})$ of the original MILP where the capacities of the bins in group $B_{\ell}$ are enlarged to $\bar{c}^{\prime}(\ell)=\bar{c}(\ell)(1+2 \delta)$ for $\ell=1, \ldots, L+N$. Notice that the first $K^{\prime}$ largest bins are enlarged to $\bar{c}_{i}^{\prime}=\bar{c}_{i}(1+3 \delta)$ (for $\left.i=1, \ldots, K^{\prime}\right)$. By considering two cases with $\operatorname{poly}(n) \leq 2^{O\left(1 / \delta^{2}(\log (1 / \delta))^{3}\right)}$ and $2^{O\left(1 / \delta^{2}(\log (1 / \delta))^{3}\right)} \leq \operatorname{poly}(n)$, the running time also can be bounded by $2^{O\left(1 / \delta^{2}(\log (1 / \delta))^{3}\right)}+\operatorname{poly}(n)$. This nice argument was used also by Downey et al. [8] for FPT algorithms.

### 4.3 Rounding the MILP solution

In this section we show how to round the MILP solution $(\bar{x}, \bar{y})$ and to pack the jobs into the enlarged bins. First, we round the $\left(x_{i}^{(\ell)}\right)$ variables for each block $B_{\ell}$ where $\ell=1, \ldots, L+N$. For bins in $B_{\ell}$ that belong to the second group $\mathcal{B}_{2}$, the values of the variables $\bar{x}_{i}^{(\ell)}$ are all integral. Let us study now a block $B_{\ell}$ that belongs to $\mathcal{B}_{3}$. Notice that again only a subset $P_{\ell}=\left\{j \in P \mid \delta(1+\delta)^{k_{j}} \in\right.$ $\left.\left(\delta(1+\delta)^{r_{\ell}},(1+\delta)^{r_{\ell}}\right]\right\}$ of job sizes that are large corresponding to $B_{\ell}$ have to be considered and that $\left|P_{\ell}\right|$ can be bounded as before by $\lfloor 2 / \delta \log (1 / \delta)\rfloor$. We denote with $\bar{m}_{\ell}$ the fractional number of bins assigned to $B_{\ell}$, i.e. $\bar{m}_{\ell}=\sum_{i} \bar{x}_{i}^{(\ell)}$. In addition, let $n_{j}^{(\ell)}$ be the fractional number of jobs of size $\delta(1+\delta)^{k_{j}}$ assigned to block $B_{\ell}$, i.e. $\sum_{i} a\left(k_{j}, \bar{C}_{i}^{(\ell)}\right) \bar{x}_{i}^{(\ell)}=n_{j}^{(\ell)}$. The total scaled area covered by the configurations is Area (large, $\ell)=\sum_{i} \bar{a}_{i, \ell} \bar{x}_{i}^{(\ell)}$. The generated solution $\left(\bar{x}_{i}^{(\ell)}\right)$ of our MILP instance satisfies the following constraints:

$$
\begin{array}{lll}
\sum_{i} x_{i}^{(\ell)} & =\bar{m}_{\ell} & \\
\sum_{i} a\left(k_{j}, \bar{C}_{i}^{(\ell)}\right) x_{i}^{(\ell)} & =n_{j}^{(\ell)} & \text { for } j \in P_{\ell} \\
\sum_{i} \bar{a}_{i, \ell} x_{i}^{(\ell)} & =\text { Area(large, } \ell) & \\
x_{i}^{(\ell)} & \geq 0 & \text { for } i=1, \ldots, h_{\ell} .
\end{array}
$$

This is a system with $\left|P_{\ell}\right|+2 \leq O(1 / \delta \log (1 / \delta))$ linear equalities where all variables $x_{i}^{(\ell)}$ should be positive. The number $q$ of variables $\bar{x}_{i}^{(\ell)}>0$ is at most $2^{O(1 / \delta \log (1 / \delta))}$ for each block $B_{\ell}$, but can be rounded down to $\left|P_{\ell}\right|+2$ without violating the linear constraints. To do this, consider a system with all $\left|P_{\ell}\right|+2$ linear constraints, but with a subset $X$ of only $\left|P_{\ell}\right|+3$ configurations with corresponding strictly positive values:

$$
\begin{array}{ll}
\sum_{\bar{C}_{i}^{(\ell)} \in X} z_{i}^{(\ell)} & =0 \\
\sum_{\bar{C}_{i}^{(\ell)} \in X} a\left(k_{j}, \bar{C}_{i}^{(\ell)}\right) z_{i}^{(\ell)} & =0 \text { for } j \in P_{\ell} \\
\sum_{i} \bar{a}_{i, \ell} z_{i}^{(\ell)} & =0
\end{array}
$$

Since we have more variables than constraints, there is a non-trivial vector $\hat{z} \neq 0$ such that the system $B \hat{z}=0$, where $B$ is the matrix describing the linear system above. We can eliminate at least one positive variable $\bar{x}_{i}^{(\ell)}$ corresponding to one of the $\left|P_{\ell}\right|+3$ variables, i.e. by using $\bar{x}=\bar{x}+\tilde{z} \delta$ where $\tilde{z}$ is the vector of dimension $q$ that corresponds to $\hat{z}$ with additional zeros and $\delta$ is appropriately chosen. Each round of eliminating one component can be done in $O\left(\mathcal{M}\left(\left|P_{\ell}\right|+3\right)\right)$ time, where $\mathcal{M}(n)$ is the time to solve a set of $n$ simultaneous linear equalities with $n$ variables. Notice that the coefficients in the system above are all integral and bounded by $O(n / \delta)$. The number of rounds is at most $q \leq 2^{O(1 / \delta \log (1 / \delta))}$. After this rounding step, we can replace the rounded configuration $\bar{C}_{i}^{(\ell)}$ by their original ones $C_{i}^{(\ell)}$. Finally we obtain a system of $\left|P_{\ell}\right|+2$ linear equalities with a set $X_{\ell}$ of $\left|P_{\ell}\right|+2$ configurations corresponding to the variables $\tilde{x}_{i}^{(\ell)}>0$ :

$$
\begin{array}{ll}
\sum_{C_{i}^{(\ell)} \in X_{\ell}} \tilde{x}_{i}^{(\ell)} & =\bar{m}_{\ell} \\
\sum_{C_{i}^{(\ell)} \in X_{\ell}} a\left(k_{j}, C_{i}^{(\ell)}\right) \tilde{x}_{i}^{(\ell)} & =n_{j}^{(\ell)} \\
\sum_{C_{i}^{(\ell)} \in X_{\ell}} \bar{a}_{i, \ell} \tilde{x}_{i}^{(\ell)} & =\text { Area(large }, \ell) .
\end{array} \quad \text { for } j \in P_{\ell}
$$

For each configuration $C_{i}^{(\ell)} \in X_{\ell}$ we round down the fractional value $\tilde{x}_{i}^{(\ell)}$ to the next integral value $\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor \geq \tilde{x}_{i}^{(\ell)}-1$. Then we use for the bin group $B_{\ell}$ exactly $\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor$ configurations of the type $C_{i}^{(\ell)}$ and place jobs of size $\delta(1+\delta)^{k_{j}}$ for $j \in P_{\ell}$ according to the multiset into the corresponding bins. For each configuration $C_{i}^{(\ell)} \in X_{\ell}$ with non-integral $\tilde{x}_{i}^{(\ell)}$ we need one additional bin to cover all $n_{j}^{(\ell)}$ jobs of size $\delta(1+\delta)^{k_{j}}$ for $j \in P_{\ell}$. For block $B_{\ell}$ let $\mathcal{J}_{\ell}$ be a collection with $\sum_{C_{i}^{(\ell)} \in X_{\ell}: \tilde{x}_{i}^{(\ell)} \text { non-integral }} a\left(k_{j}, C_{i}^{(\ell)}\right)$ jobs of size $\delta(1+\delta)^{k_{j}}$ for $j \in P_{\ell}$. This set of jobs will be executed later on the $K$ fastest machines. Using the rounding we have immediately:

$$
\begin{array}{ll}
\sum_{C_{i}^{(\ell)} \in X_{\ell}}\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor & \leq \bar{m}_{\ell}, \\
\sum_{C_{i}^{(\ell)} \in X_{\ell}} a\left(k_{j}, C_{i}^{(\ell)}\right)\left\lceil\tilde{x}_{i}^{(\ell)}\right\rceil & \geq\left\lceil n_{j}^{(\ell)}\right\rceil \quad \text { for } j \in P_{\ell}, \\
\sum_{C_{i}^{(\ell)} \in X_{\ell}} \bar{a}_{i, \ell}\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor & \leq \text { Area(large, } \ell) .
\end{array}
$$

The nice properties of the rounded solution are that we use less than or equal to $\bar{m}_{\ell}$ bins and have a total area bounded by the fractional solution. Notice that the solution maybe covers more jobs than the fractional solution, i.e. it covers an integral number of at least $\left\lceil n_{j}^{(\ell)}\right\rceil \geq n_{j}^{(\ell)}$ jobs of size $\delta(1+\delta)^{k_{j}}$. Thus, we have proved the following result.

Lemma 4.6 We can round in time polynomial in $n$ and $1 / \delta$ a feasible solution $(\bar{x}, \bar{y})$ of the MILP into another solution $(\tilde{x}, \bar{y})$ such that the following constraints are satisfied:

$$
\begin{array}{lll}
\sum_{i}\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor & \leq m_{\ell} & \text { for } \ell=1, \ldots, L+N \\
\sum_{\ell, i} a\left(k_{j}, C_{i}^{(\ell)}\right)\left\lceil\tilde{x}_{i}^{(\ell)}\right\rceil+\sum_{\ell=0}^{a_{j}-1} \bar{y}_{j, \ell} & \geq n_{j} & \text { for } j=P^{\prime}+1, \ldots, P \\
\sum_{i} \bar{a}_{i, \ell}\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor+\sum_{j: \ell<a_{j}} \bar{b}_{j, \ell} \bar{y}_{j, \ell} & \leq\left\lfloor\frac{m_{\ell}(1+2 \delta)(2 n)}{\delta}\right\rfloor & \text { for } \ell=1, \ldots, L+N \\
\sum_{j=P^{\prime}+1}^{P} \bar{b}_{j, 0} \bar{y}_{j, 0} & \leq\left\lfloor\frac{\bar{S}_{0}^{(n e w)}(2 n)}{\delta \bar{c}(1)}\right\rfloor, &
\end{array}
$$

where $\tilde{x}_{i}^{(\ell)} \geq 0$ and $\bar{y}_{j, \ell} \geq 0$. Furthermore, the number of strictly positive values $\tilde{x}_{i}^{(\ell)}>0$ is at most $O(1 / \delta \log (1 / \delta))$ for each block $B_{\ell}$ in $\mathcal{B}_{3}$.

Notice that the number of strictly positive values $\tilde{x}_{i}^{(\ell)}=\bar{x}_{i}^{(\ell)}$ for all blocks in $\mathcal{B}_{2}$ is at most $O\left(1 / \delta \log (1 / \delta)^{2}\right)$ (due to the choice in the MILP instance and since we have not rounded these values).

The next step is to round the $\left(\bar{y}_{j, \ell}\right)$ values of the MILP over all bin groups $B_{\ell}$ and job sizes $j \in\left\{P^{\prime}+1, \ldots, P\right\}$. Since the values $\bar{y}_{j, \ell}=n_{j}$ are integral for each $j \leq P^{\prime}$, we have to round only the other variables $\bar{y}_{j, \ell}$ with $j>P^{\prime}$. Let $N_{j}$ be the fractional total number of jobs assigned as a small job of size $\delta(1+\delta)^{k_{j}}$ to the blocks (i.e. $N_{j}=\sum_{\ell=0}^{a_{j}-1} \bar{y}_{j, \ell}$ for $j=P^{\prime}+1, \ldots, P$ ). In addition let Area (small, $\ell$ ) be the corresponding total scaled area of small jobs in bin group $B_{\ell}$ (i.e. $\operatorname{Area}($ small, $\ell)=\sum_{j: \ell<a_{j}} \bar{b}_{j, \ell} \bar{y}_{j, \ell}$ for $\ell=1, \ldots, L+N$ ). For group $B_{0}$ (these are the first $K$ or $K^{\prime}$ bins) we denote with $\operatorname{Area}\left(\right.$ small, 0 ) the total scaled area of the assigned jobs $\sum_{j=P^{\prime}+1}^{P} \bar{b}_{j, 0} \bar{y}_{j, 0}$. Then our values ( $\bar{y}_{j, \ell}$ ) satisfy the following system of (in-)equalities:

$$
\begin{array}{lll}
\sum_{\ell=0}^{a_{j}-1} y_{j, \ell} & =N_{j} & \text { for } j=P^{\prime}+1, \ldots, P, \\
\sum_{j: \ell<a_{j}} \bar{b}_{j, \ell} y_{j, \ell} & =\operatorname{Area}(\text { small }, \ell) & \text { for } \ell=1, \ldots, L+N, \\
\sum_{j=P^{\prime}+1}^{P} \bar{b}_{j, 0} y_{j, 0} & =\text { Area(small, } 0) & \\
y_{j, \ell} & \geq 0 & \text { for } j=P^{\prime}+1, \ldots, P \text { and } \ell=0, \ldots, L+N .
\end{array}
$$

If Area $($ small,$\ell)=0$, then we can simply remove the corresponding inequality and the variables. Since the index $a_{j}>0$ for all $j=P^{\prime}+1, \ldots, P$ and $a_{j}=0$ for all $j=1, \ldots, P^{\prime}$, the equality for block $B_{0}$ can be written as $\sum_{j: 0<a_{j}} \bar{b}_{j, 0} y_{j, 0}=\operatorname{Area}($ small, 0$)$. Notice that we can reduce our $\bar{y}_{j, \ell}$ values such that they satisfy also the following system:

$$
\begin{array}{lll}
\sum_{\ell=0}^{a_{j}-1} y_{j, \ell} & =\left\lfloor N_{j}\right\rfloor & \text { for } j=P^{\prime}+1, \ldots, P, \\
\sum_{j: \ell<a_{j}} b_{j, \ell} y_{j, \ell} & \leq \text { Area(small, }) & \text { for } \ell=0, \ldots, L+N, \\
y_{j, \ell} & \geq 0 & \text { for } j=P^{\prime}+1, \ldots, P \text { and } \ell=0, \ldots, L+N .
\end{array}
$$

Since we have rounded up for each block $B_{\ell}$ and size $p \in P_{\ell}$ the $x_{i}^{(\ell)}$ values of the configurations and obtained $\sum_{\ell}\left\lceil n_{j}^{(\ell)}\right\rceil$ jobs of size $\delta(1+\delta)^{k_{j}}$ (for each $j \geq P^{\prime}+1$ ), it is sufficient to cover only $\left\lfloor N_{j}\right\rfloor$ jobs of the same size in this step. Therefore, our rounded solution will cover all $n_{j}$ jobs. Now set $y_{j, \ell}^{\prime}=y_{j, \ell} /\left\lfloor N_{j}\right\rfloor$ and obtain the following linear system:

$$
\begin{array}{ll}
\sum_{\ell=0}^{a_{j}-1} y_{j, \ell}^{\prime} & =1 \text { for } j=P^{\prime}+1, \ldots, P, \\
\sum_{j j, \ell<a_{j}} & \leq 1 \text { for } \ell=0, \ldots, L+N, \\
y_{j, \ell}^{\prime} & \geq 0 \text { for } j=P^{\prime}+1, \ldots, P \text { and } \ell=0, \ldots, L+N .
\end{array}
$$

This system of (in-)equalities can be interpreted as a scheduling problem on ( $L+N+1$ ) unrelated machines with makespan 1 , and the solution can be rounded into another solution ( $\hat{y}_{j, \ell}$ ) such that all constraints are still satisfied and that each machine $\ell$ gets at most one fractional job with $\hat{y}_{j, \ell} \in(0,1)[29,32]$. Here we round each fractional scaled value Area (small, $\ell$ ) to the next integer Area $^{\prime}($ small,$\ell)<$ Area $($ small, $\ell)+1$. After this rounding, the coefficients in the inequalities above are all rational numbers with nominator and denominator bounded by a polynomial in $n$ and $1 / \delta$. Then the rounding step in the scheduling algorithm [29,32] can be done in time polynomial in $n$ and $1 / \delta$.

If a value $\hat{y}_{j, \ell} \in\{0,1\}$ is in the solution, then the corresponding value $\tilde{y}_{j, \ell}=\left\lfloor N_{j}\right\rfloor \hat{y}_{j, \ell}$ is either 0 or $\left\lfloor N_{j}\right\rfloor$. Now there are two cases depending on whether there is a fractional variable $\hat{y}_{j, \ell}$ assigned to block $B_{\ell}$ or not. In the first case let $\hat{y}_{j,, \ell} \in(0,1)$ for a job size with $\bar{b}_{j, \ell} \geq 1$. Here the corresponding value $\tilde{y}_{j, \ell} \in\left(0,\left\lfloor N_{j}\right\rfloor\right)$. We round now these values (at most one for each machine or block $B_{\ell}$ )
to the next integral value $\left\lfloor\tilde{y}_{j e, \ell}\right\rfloor$ and place $\left\lfloor\tilde{y}_{j, \ell}\right\rfloor$ many jobs of size $\delta(1+\delta)^{k_{j}}$ into bin group $B_{\ell}$. This implies that $\sum_{j}\left\lfloor\tilde{y}_{j, \ell}\right\rfloor \bar{b}_{j, \ell} \leq \operatorname{Area}($ small, $\ell)$. In the second case we have only integral variables assigned to group $B_{\ell}$ and the sum $\sum_{j} \hat{y}_{j, \ell}\left\lfloor N_{j}\right\rfloor \bar{b}_{j, \ell}$ could be equal to $\operatorname{Area}^{\prime}($ small, $\ell)$. If this happens for any machine or block $B_{\ell}$, we take out one job of size $\delta(1+\delta)^{k_{j \ell}}$ where $\tilde{y}_{j_{\ell, \ell}}=\left\lfloor N_{j_{\ell}}\right\rfloor \geq 1$ and $\bar{b}_{j_{\ell, \ell}} \geq 1$. Since the rounded scaled area $\operatorname{Area}^{\prime}($ small, $\ell) \geq 1$, there always exists such a job. After that we reduce the corresponding value $\tilde{y}_{j_{\ell, \ell}}$ to $\left\lfloor N_{j_{\ell}}\right\rfloor-1 / 2$. Let $\mathcal{J}_{B}$ be a collection with one job of size $\delta(1+\delta)^{k_{j}}$ for each fractional variable $\tilde{y}_{j, \ell}$. These jobs are executed later as additional jobs on one of the machines in group $B_{\ell}$. Furthermore, the following constraints are satisfied:

$$
\begin{array}{ll}
\sum_{j}\left\lfloor\tilde{y}_{j, \ell}\right\rfloor \bar{b}_{j, \ell} \leq \text { Area }(\text { small }, \ell) & \text { for } \ell=0, \ldots, L+N, \\
\sum_{\ell=0}^{a_{j}-1}\left\lceil\tilde{y}_{j, \ell}\right\rceil \geq\left\lfloor N_{j}\right\rfloor & \text { for } j=P^{\prime}+1, \ldots, P .
\end{array}
$$

After both rounding phases and replacing the rounded job sizes by their original ones we obtain:
Lemma 4.7 We can round a feasible solution $(\bar{x}, \bar{y})$ of the MILP into another solution ( $\tilde{x}, \tilde{y})$ such that the following holds:

$$
\begin{array}{lll}
\sum_{i}\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor & \leq m_{\ell} & \text { for } \ell=1, \ldots, L+N \\
\sum_{\ell, i} a\left(k_{j}, C_{i}^{(\ell)}\right)\left\lceil\tilde{x}_{i}^{(\ell)}\right\rceil+\sum_{\ell=0}^{a_{j}-1}\left\lceil\tilde{y}_{j, \ell}\right\rceil & \geq n_{j} & \text { for } j=P^{\prime}+1, \ldots, P \\
\sum_{i} \operatorname{size}\left(C_{i}^{(\ell)}\right)\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor+\sum_{j: \ell<a_{j}}\left\lfloor\tilde{y}_{j, \ell}\right\rfloor \delta(1+\delta)^{k_{j}} & \leq m_{\ell} \bar{c}(\ell)(1+2 \delta) & \text { for } \ell=1, \ldots, L+N \\
\sum_{j=P^{\prime}+1}^{P}\left\lfloor\tilde{y}_{j, 0}\right\rfloor \delta(1+\delta)^{k_{j}} & \leq \bar{S}_{0}^{(\text {new })}, &
\end{array}
$$

where $\tilde{x}_{i}^{(\ell)} \geq 0$ and $\tilde{y}_{j, \ell} \geq 0$. Furthermore, $\left|\left\{i \mid x_{i}^{(\ell)}>0\right\}\right| \leq O(1 / \delta \log (1 / \delta))$ for each block $B_{\ell}$ in $\mathcal{B}_{3}$. Furthermore, for each block $B_{\ell}$ with $\ell \in\{0, \ldots, L+N\}$ there is at most one fractional variable $\tilde{y}_{j, \ell}$.

### 4.4 Packing the jobs via the rounded MILP solution

As in the special case before (see Section 3), we place in a first phase the jobs as large ones according to the configurations and $\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor$ values and in a second phase the jobs as small ones according to the $\left\lfloor\tilde{y}_{j, \ell}\right\rfloor$ values in slightly enlarged bins. In the third phase we place the tiny jobs in $\mathcal{J}_{\text {tiny }}$ in the free space of the bins. This can be done due to the rounding phases and the area constraints. In the placement phases of the small and tiny jobs we have to enlarge the capacities $\bar{c}^{\prime}(\ell)=\bar{c}(\ell)(1+2 \delta)$ of the bins to $\bar{c}^{\prime}(\ell)(1+\delta)$ for each bin in $B_{\ell}$. In addition, we have to enlarge the capacities of the first $K^{\prime}$ bins to $\bar{c}_{i}^{\prime}(1+\delta)$. After this step we place the set $\mathcal{J}_{B}$ on the machines: for each non-integral value $\tilde{y}_{j, \ell}$ we place a job of size $\delta(1+\delta)^{k_{j}}$ on one machine in group $B_{\ell}$. Since for each group $B_{\ell}$ there is at most one job size $j \in\left\{P^{\prime}, \ldots, P\right\}$ with $\tilde{y}_{j, \ell}$ non-integral and this size is small corresponding to the group $B_{\ell}$, this increases the size of one bin in $B_{\ell}$ from $\bar{c}^{\prime}(\ell)(1+\delta)$ to $\bar{c}^{\prime}(\ell)(1+2 \delta)$. Since we could have also one job size for group $B_{0}$, the size of one of the largest $K$ bins is also increased to $\bar{c}_{i}^{\prime}(1+2 \delta)$.

Finally, we bound the total execution time of the non-placed jobs in $\cup_{\ell} \mathcal{J}_{\ell}$. For each block $B_{\ell}$ in $\mathcal{B}_{3}$ with $\ell=L+1, \ldots, L+N$ we obtain $\left|P_{\ell}\right|+2=\lfloor 2 / \delta \log (1 / \delta)\rfloor+2$ additional bins of size $\bar{c}^{\prime}(\ell)=\bar{c}(\ell)(1+2 \delta) \leq(1+\delta)^{r_{\ell}+2}$. These bins or the corresponding jobs are placed later on the first $K$ machines. In this step we use also the machines $K^{\prime}+1, \ldots, K$. Let us specify $K:=\lfloor 2 / \delta \log (1 / \delta)\rfloor+2$. Now take one bin per group and estimate the total size of these bins among all groups $\ell=L+1, \ldots, L+N$. Using the order $r_{L+1}>r_{L+2}>\ldots>r_{L+N}$, the inequality $r_{(L+1)+\ell} \leq r_{(L+1)}-\ell$, and the geometric series, we obtain

$$
\begin{aligned}
& \sum_{\ell=L+1}^{L+N} \bar{c}(\ell)=\sum_{\ell=L+1}^{L+N}(1+\delta)^{r_{\ell}} \leq \sum_{\ell \ell=0}^{N-1}(1+\delta)^{r_{L+1}-\ell}=(1+\delta)^{r_{L+1}} \sum_{\ell=0}^{N-1} \frac{1}{(1+\delta)^{\ell}} \\
& \leq(1+\delta)^{r_{L+1}} \sum_{\ell=0}^{\infty} \frac{1}{(1+\delta)^{\ell}}=(1+\delta)^{r_{L+1}} /(1-1 /(\delta+1))=(1+\delta)^{r_{L+1}+1} / \delta .
\end{aligned}
$$

Therefore, the sum of the enlarged bin sizes $\sum_{\ell=L+1}^{L+N} \bar{c}(\ell)(1+\delta)^{2} \leq(1+\delta)^{r}(L+1)+3 / \delta$. Now we have $(1+\delta)^{r_{L+1}+3} / \delta \leq \delta c_{K}^{\prime}$, if and only if $(1+\delta)^{r_{L+1}} \leq \delta^{2} /(1+\delta)^{3} c_{K}^{\prime}$. Note that $(1+\delta)^{r_{L+1}}=$ $\bar{c}(L+1)=\bar{c}_{K+G+1}=c_{K+G+1}^{\prime}=c_{\max }\left(\mathcal{B}_{3}\right), c_{K}^{\prime}=c_{\min }\left(\mathcal{B}_{1}\right)$ and $c_{\max }\left(\mathcal{B}_{3}\right) \leq \gamma c_{\min }\left(\mathcal{B}_{1}\right)$ using the gap construction in Section 2. The property above is satisfied for $\gamma \leq \delta^{2} /(1+\delta)^{3}$. Therefore, we specify $\gamma:=\delta^{2} /(1+\delta)^{3}$. In this case the sum of the capacities above is bounded by $\delta$ times the minimum capacity among bins in $\mathcal{B}_{1}$. In other words, we can take one bin per group $B_{\ell}$ among all groups in $\mathcal{B}_{3}$ and the corresponding jobs and place them on one of the $K$ machines. Since the total size of these jobs is at most $\delta c_{K}^{\prime}$, this enlarges the size of the ith bin from $\bar{c}_{i}^{\prime}(1+2 \delta)$ to $\bar{c}_{i}^{\prime}(1+2 \delta)+\delta c_{K}^{\prime} \leq \bar{c}_{i}^{\prime}(1+3 \delta)$ for $i=1, \ldots, K$. Using $\bar{c}^{\prime}(\ell)=\bar{c}(\ell)(1+2 \delta)$ for $\ell=1, \ldots, L+N$ and $\bar{c}_{i}^{\prime}=\bar{c}_{i}(1+3 \delta)$ for $i=1, \ldots, K$, we obtain the following result:

Lemma 4.8 If there is a feasible solution of an MILP instance with bin capacities $\bar{c}(\ell)$ for blocks $B_{\ell} \in \mathcal{B}_{2} \cup \mathcal{B}_{3}$ and capacities $\bar{c}_{i}$ for the first $K$ largest bins, then the entire job set $\mathcal{J}$ can be packed into bins with enlarged capacities $\bar{c}(\ell)(1+2 \delta)^{2}$ for blocks $B_{\ell} \in \mathcal{B}_{2} \cup \mathcal{B}_{3}$ and enlarged capacities $\bar{c}_{i}(1+3 \delta)^{2}$ for the first $K$ bins.

The main algorithm for scenario 3 works as follows:
given: bin set $\mathcal{B}_{1}^{\prime}=\left\{b_{1}, \ldots, b_{K^{\prime}}\right\}, \mathcal{B}_{1} \backslash \mathcal{B}_{1}^{\prime}=\left\{b_{K^{\prime}+1}, \ldots, b_{K}\right\}, \mathcal{B}_{2}=\left\{b_{K+1}, \ldots, b_{K+G}\right\}$ and $\mathcal{B}_{3}=$ $\left\{b_{K+G+1}, \ldots, b_{m}\right\}$.
(0) if $\sum_{j=1}^{n} \bar{p}_{j}>\sum_{i=1}^{m} \bar{c}_{i}$ then assert that there is no solution for the makespan and stop.
(1) remove the tiny jobs with size $\leq \delta \bar{c}_{m}$ and try to pack the huge jobs with size $>\delta \bar{c}_{K^{\prime}}$ into the first $K^{\prime}$ enlarged bins in $\mathcal{B}_{1}^{\prime}$.
(2) if there is a feasible packing for the huge jobs into the enlarged $K^{\prime}$ bins then
(2.1) for each choice with $O\left(1 / \delta \log (1 / \delta)^{2}\right)$ integral $x_{i}^{(\ell)}$ - variables in $\mathcal{B}_{2}$
(2.1.1) set up the modified small MILP with bounded coefficients,
(2.1.2) apply the algorithm by Kannan to the MILP instance with the separation oracle and store a solution (if there is any),
(2.2) if there is at least one feasible solution $(\bar{x}, \bar{y})$ then
(2.2.1) round the fractional $\left(\bar{x}_{i}^{(\ell)}\right)$ values as described in Section 4.3 to $\left(\tilde{x}_{i}^{(\ell)}\right)$ with less components, round down these values to the next integral values and store $\mathcal{J}_{\ell}$ for $\ell=L+1, \ldots, L+N$,
(2.2.2) round the ( $\bar{y}_{j, \ell}$ ) values as described in Section 4.3 to ( $\tilde{y}_{j, \ell}$ ) and store $\mathcal{J}_{B}$,
(2.2.3) pack the jobs via the rounded $\left\lfloor\tilde{x}_{i}^{(\ell)}\right\rfloor$ values for $\ell=L+1, \ldots, L+N$ and the original integral $\bar{x}_{i}^{(\ell)}$ values for $\ell=1, \ldots, L$ as large items,
(2.2.4) pack the jobs via the rounded $\left\lfloor y_{j, \ell}\right\rfloor$ values for $\ell=0, \ldots, L+N$ and the tiny jobs as small items into the enlarged bins,
(2.2.5) pack the sets $\mathcal{J}_{B}$ and $\cup_{\ell} \mathcal{J}_{\ell}$ as described in Section 4.4, and assert that there is a solution with the approximate makespan (and output the corresponding packing). otherwise assert that there is no solution for the makespan.
otherwise assert that there is no solution for the makespan.

If there is a schedule with makespan at most $T$ (and with corresponding bin sizes $c_{i}$ ), then the Lemma above implies a packing into bins of size at most $c_{i}(1+\delta)^{3}(1+3 \delta)^{2}$ and a corresponding schedule of length $T(1+\delta)^{3}(1+3 \delta)^{2} \leq O P T(1+\delta)^{4}(1+3 \delta)^{2} \leq O P T(1+16 \delta) \leq O P T(1+\epsilon)$ for $\delta \leq \epsilon / 16$ and $\epsilon \leq 1$. We simply set $\delta=\frac{1}{\lceil 16 / \epsilon\rceil}$ and obtain $\delta \leq \epsilon / 16, \delta \geq \epsilon /(16+\epsilon) \geq \epsilon /(16+1)$ and that $1 / \delta=\lceil 16 / \epsilon\rceil$ is integral.

The algorithm for scenario 4 works in a similar way (again we can use an MILP relaxation, but do not need the huge jobs). For this case there are only two groups of bins $\mathcal{B}_{1}^{\prime} \cup \mathcal{B}_{2}$ and $\mathcal{B}_{3}$. The first group has a constant number of different capacities such that we get again a small constant number of integral variables. For the rounding step we use again the property that there is a gap of $1 / \gamma$ between $c_{\text {min }}\left(\mathcal{B}_{1}\right)$ and $c_{\text {max }}\left(\mathcal{B}_{3}\right)$.
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